CSC 162 DATA STRUCTURES

Traversing graphs

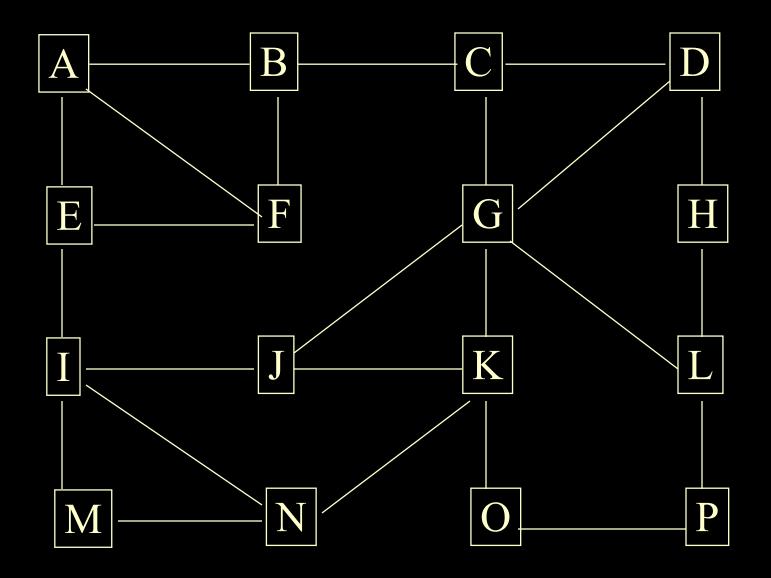
Depth-First Search like a post-order traversal of a tree

Breadth-First Search

Less like tree traversal

Exploring a Maze

A depth-first search (DFS) in an undirected graph G is like wandering in a maze with a string and a can of paint – you can prevent yourself from getting lost.

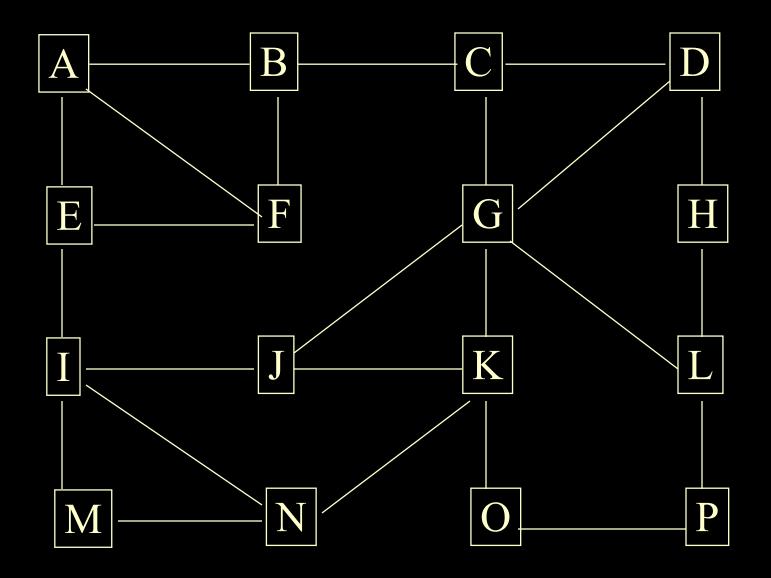


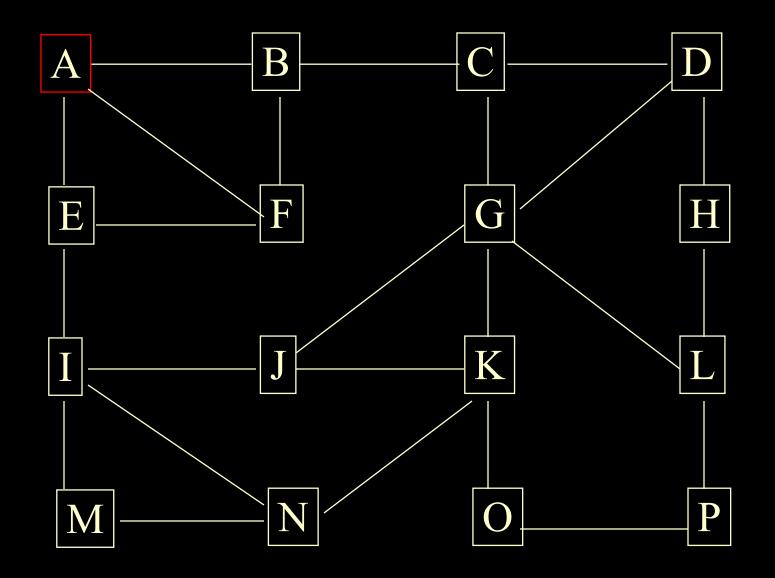
DFS

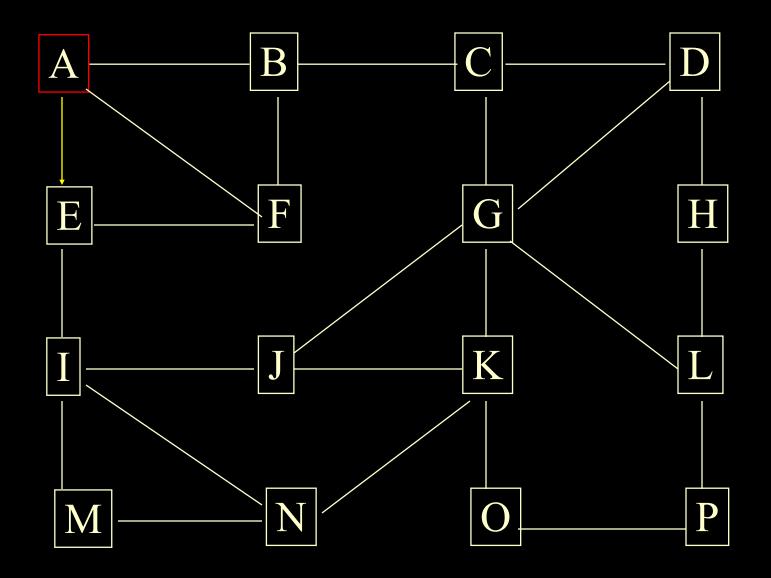
- 1. Start at vertex s
 Tie the end of the string to s and mark "visited" on s
 Make s the current vertex u
- 2. Travel along an arbitrary edge (u,v) unrolling string
- 3. If edge(u,v) leads to an already visited vertex v then return to u else mark v as "visited", set v as current u, repeat @ step 2
- 4. When all edges lead to visited verticies, backtrack to previous vertex (roll up string) and repeat @ step 2
- 5. When we backtrack to s and explore all it's edges we are done

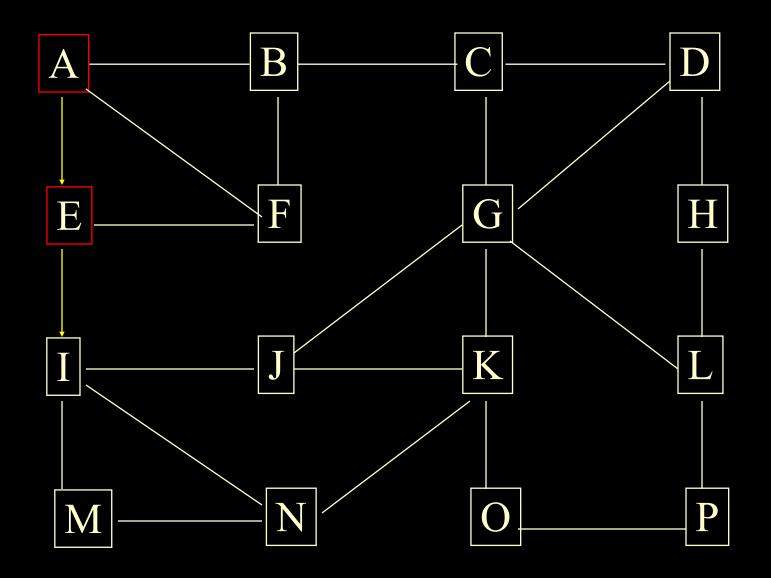
DFS Pseudocode (labels edges)

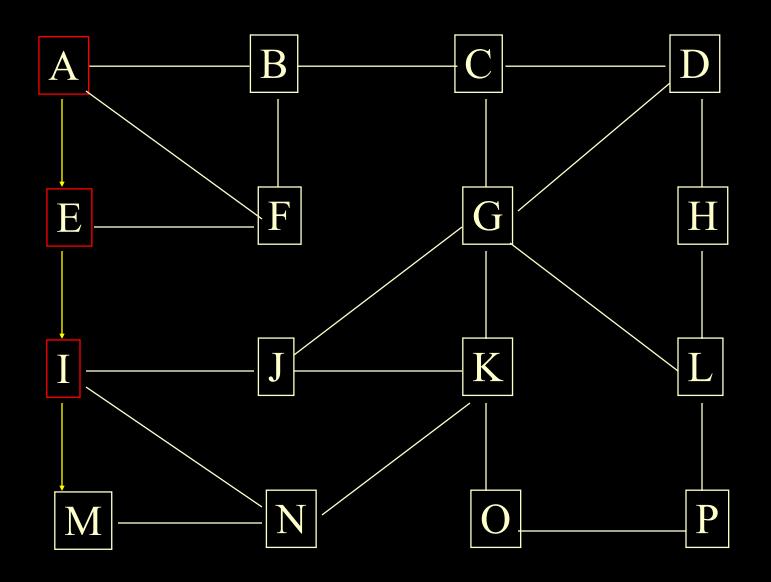
```
DFS(Vertex v)
  for each edge incident on v do:
     if edge e is unexplored then
           let w be the other endpoint of e
           if vertex w is unexplored then
                 label e as a discovery edge
                 recursively call DFS(w)
           else
                 label e as a backedge
```

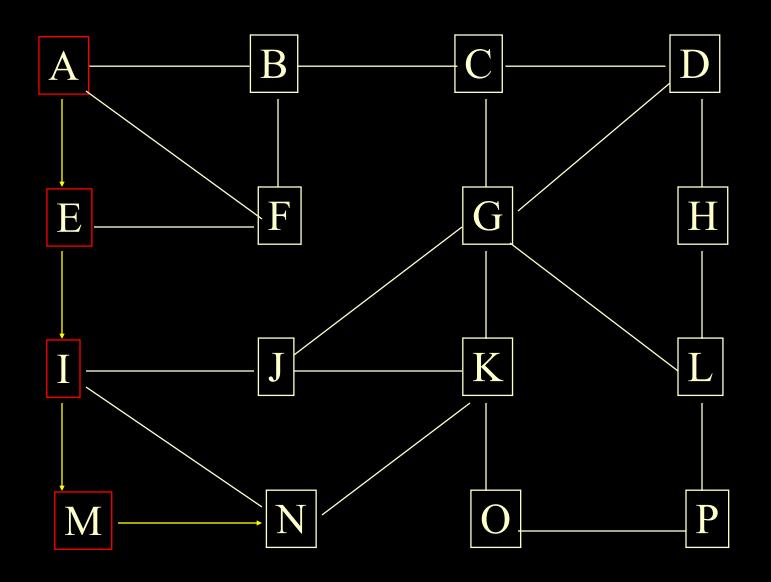


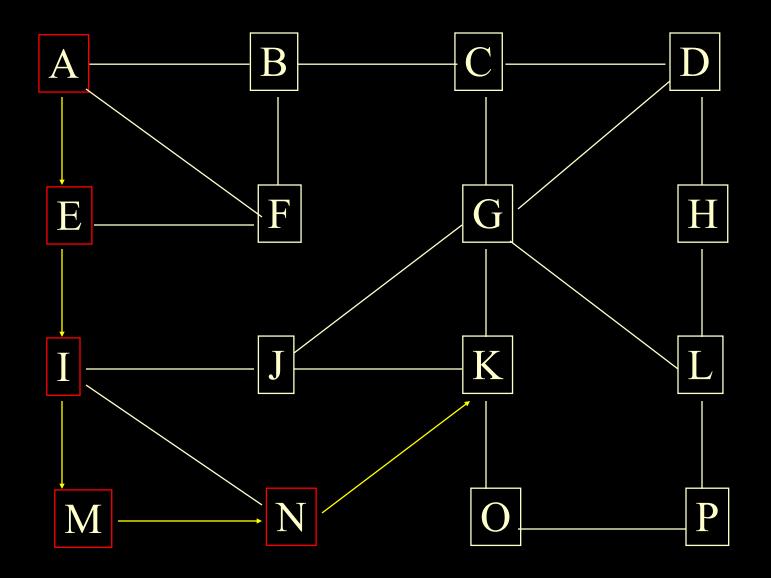


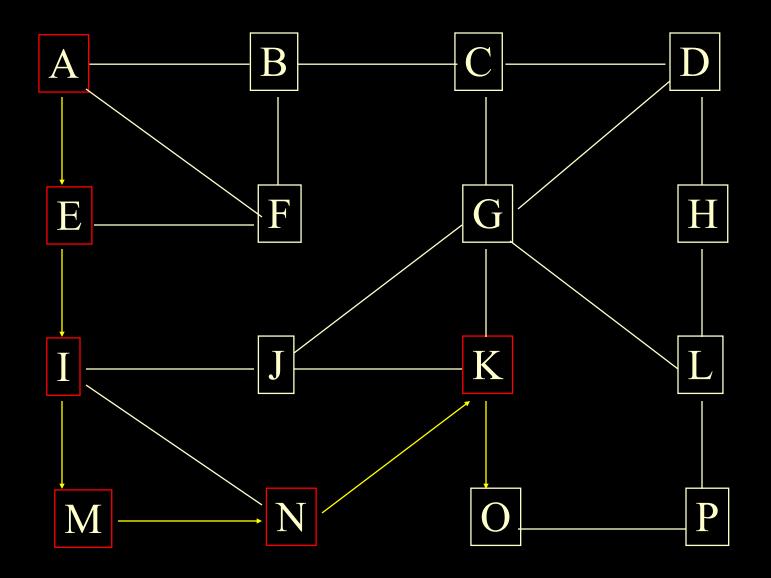


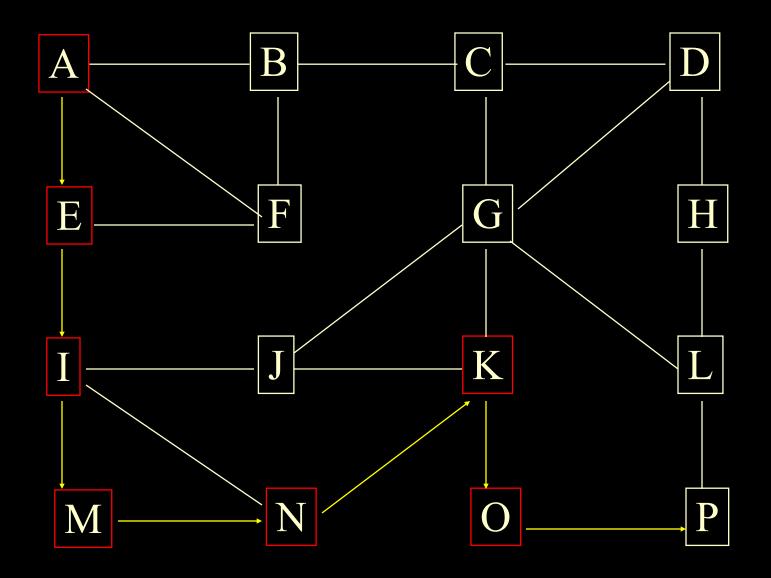


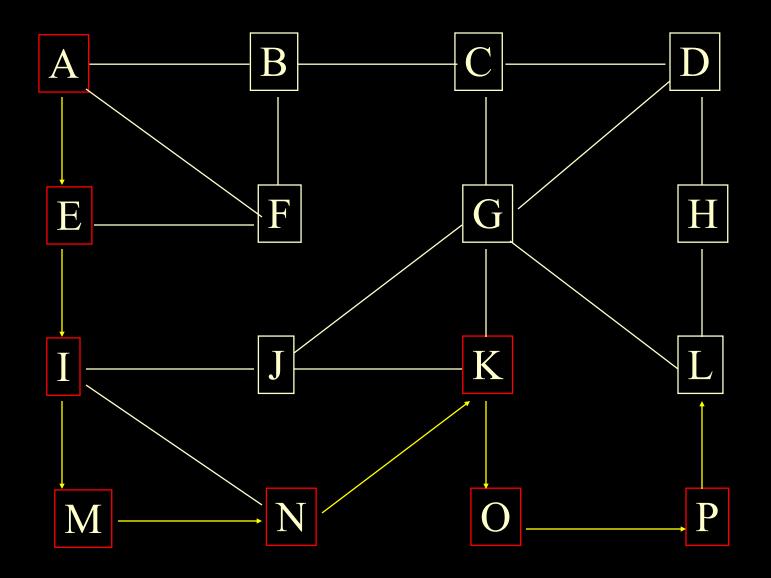


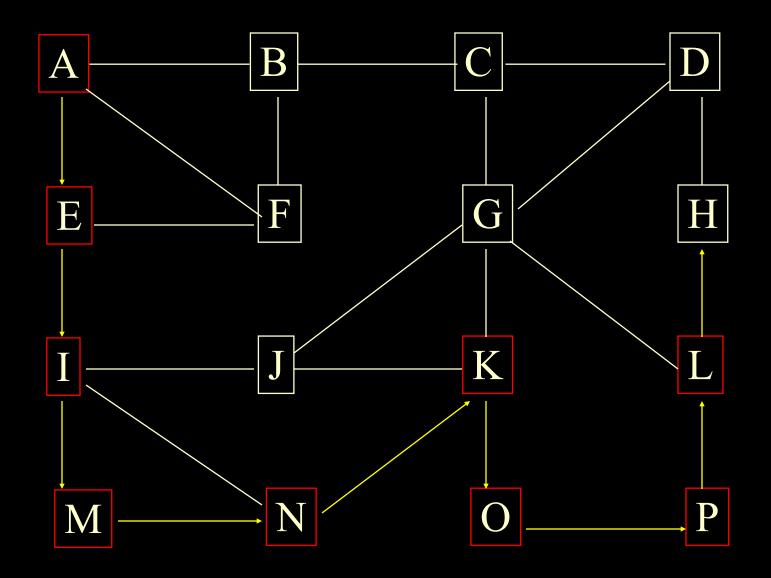


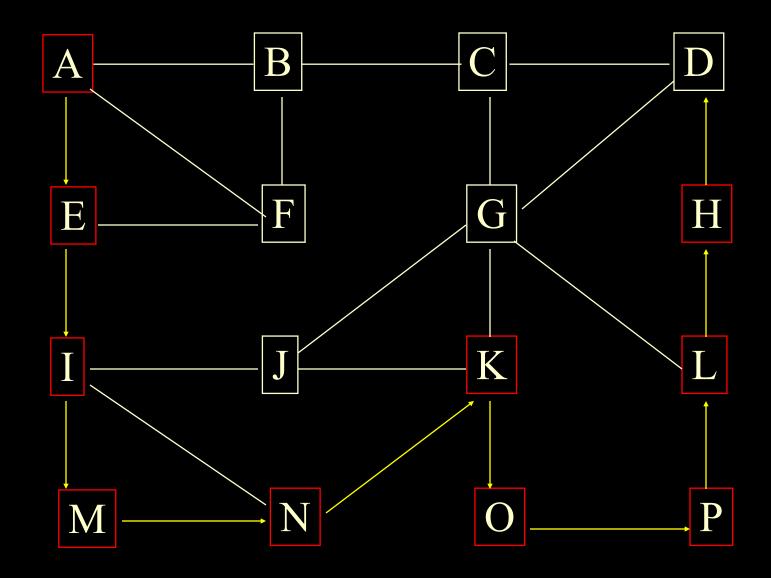


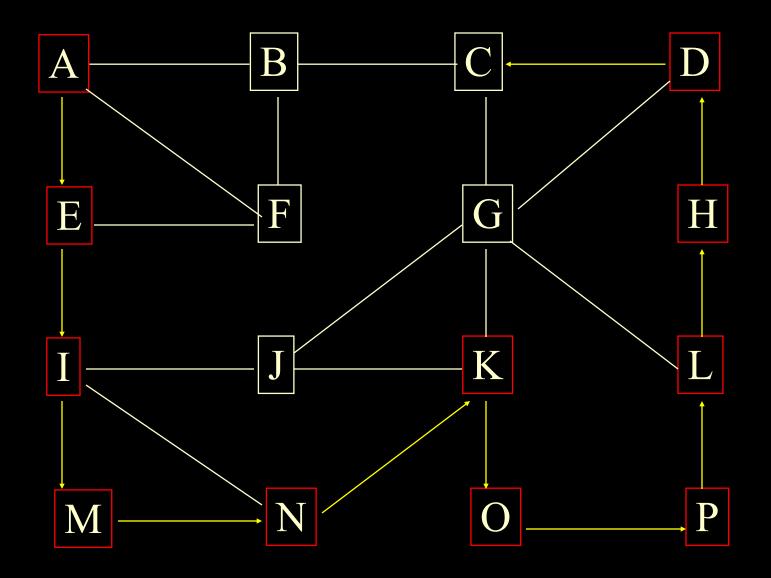


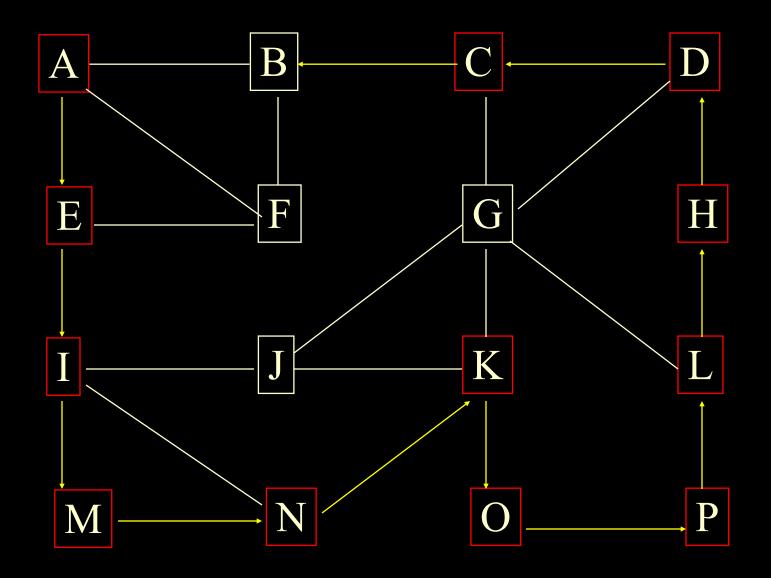


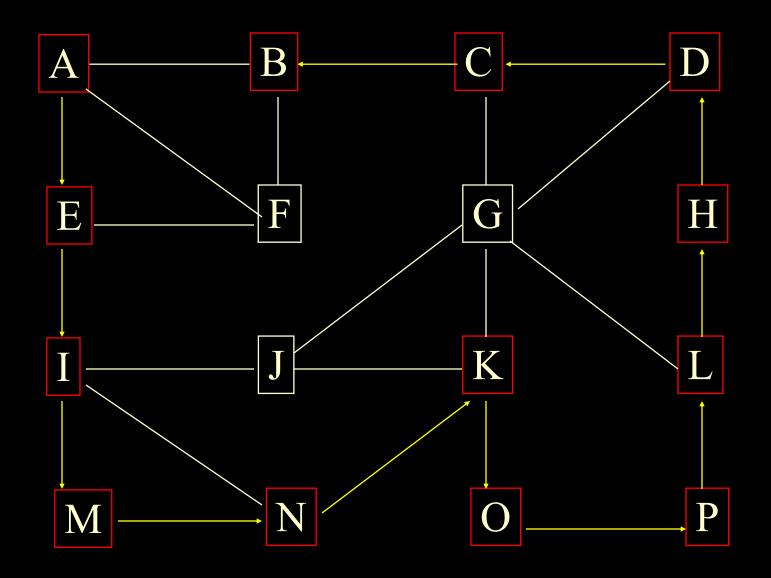


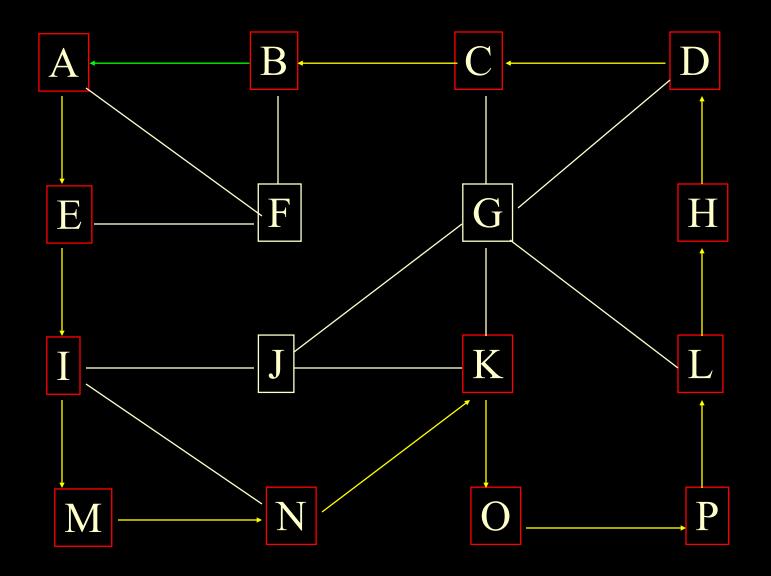


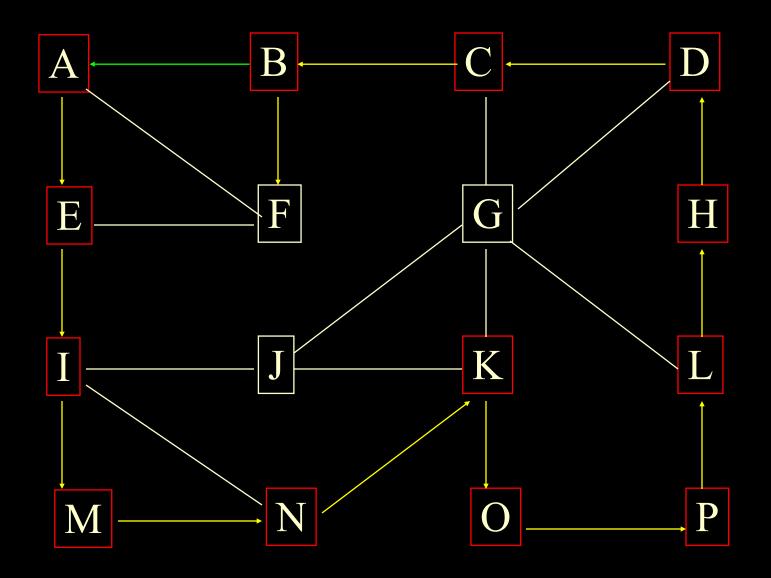


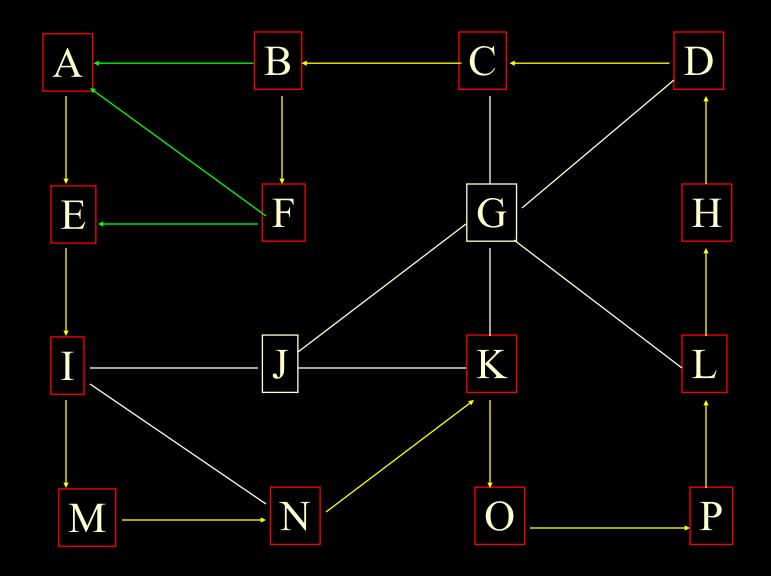


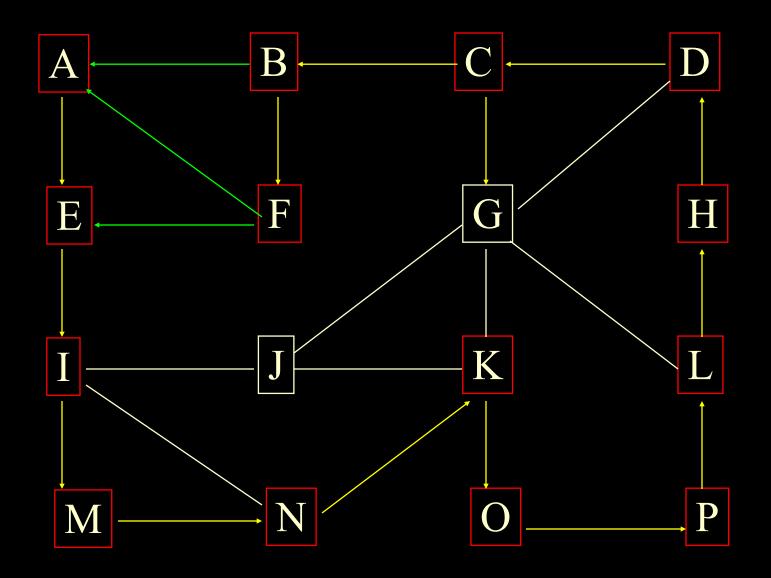


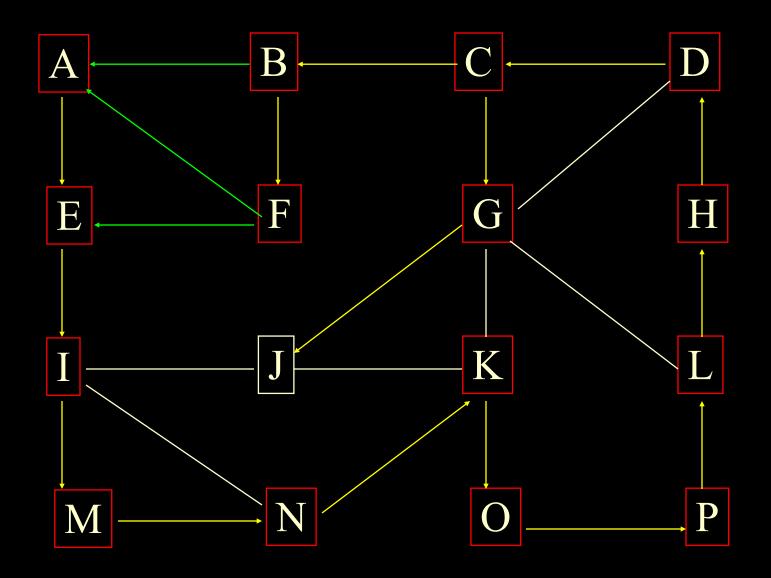


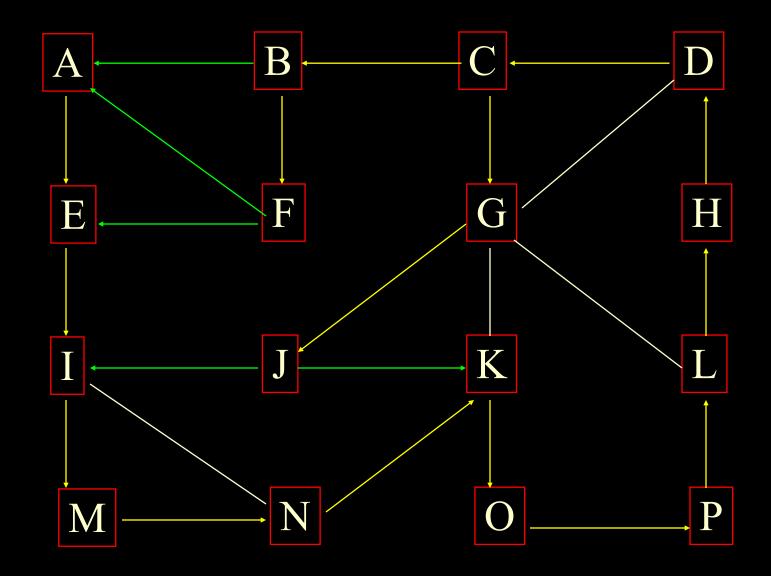


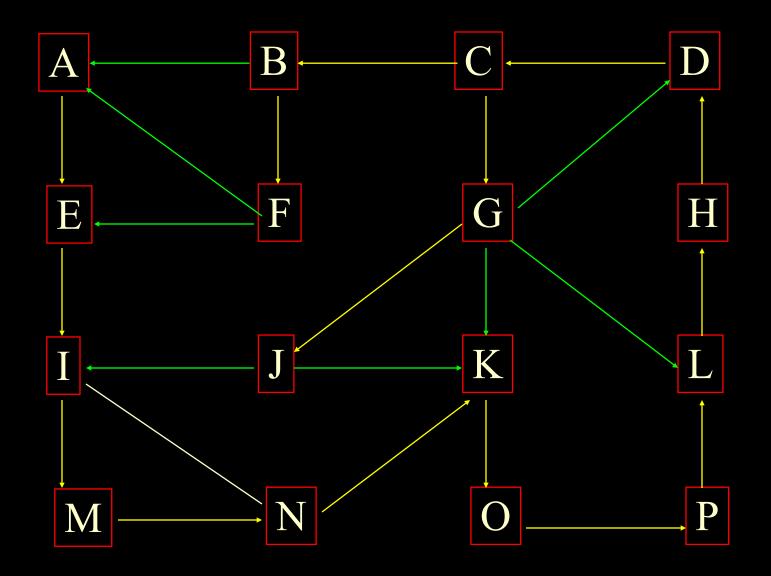


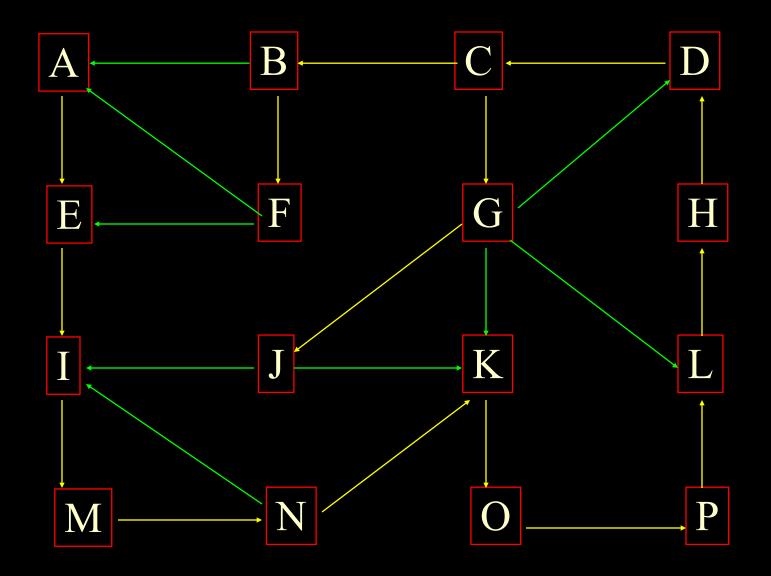




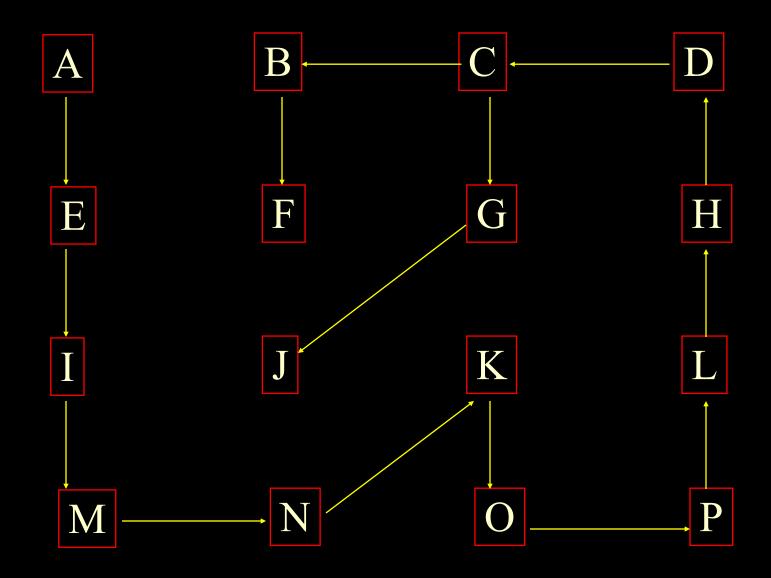








DFS Tree



DFS Properties

Starting at s

The traversal visits al the vertices in the connected component of s

The discovery edges form a spanning tree of the connected component of s

DFS Runtime

- DFS is called on each vertex exactly once
- Every edge is examined exactly twice (once from each of its vertices)
- So, for n_s vertices and m_s edges in the connected component of the vertex s, the DFS runs in $O(n_s+m_s)$ if:
 - The graph data structure methods take constant time
 - Marking takes constant time
 - There is a systematic way to examine edges (avoiding redundancy)

Marking Verticies

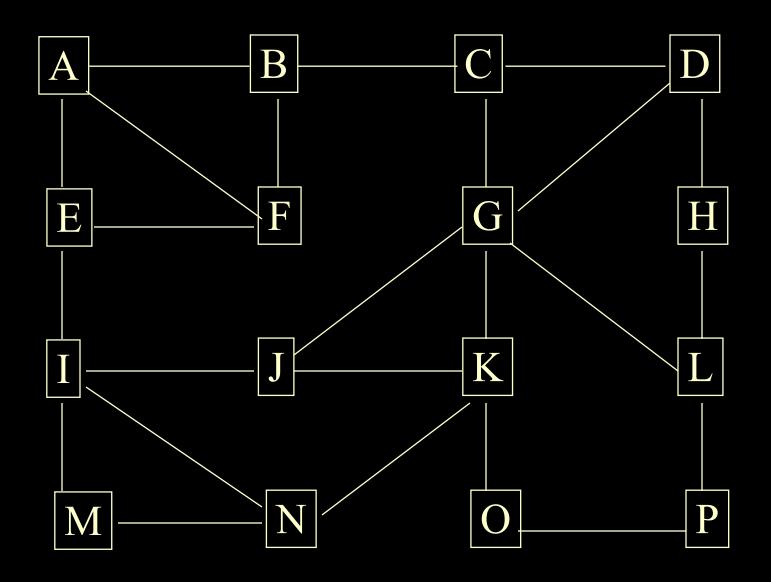
Extend vertex structure to support variable for marking

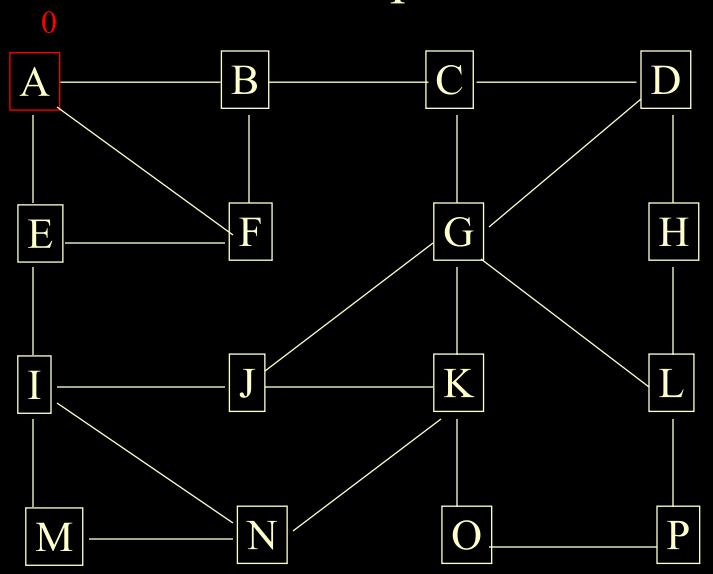
Use a hash table mechanism to log marked vertices

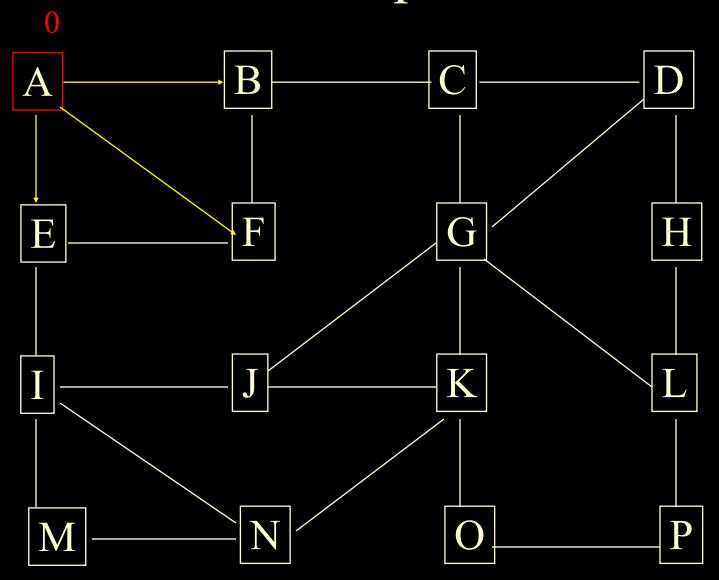
Breadth-First Search

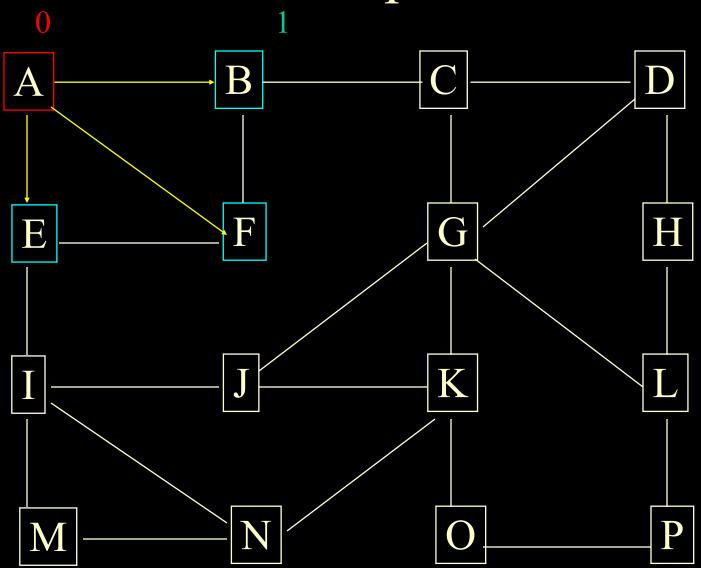
```
Starting vertex has level 0 (anchor vertex)
Visit (mark) all vertices that are only one edge away
mark each vertex with its "level"
One edge away from level 0 is level 1
One edge away from level 1 is level 2
```

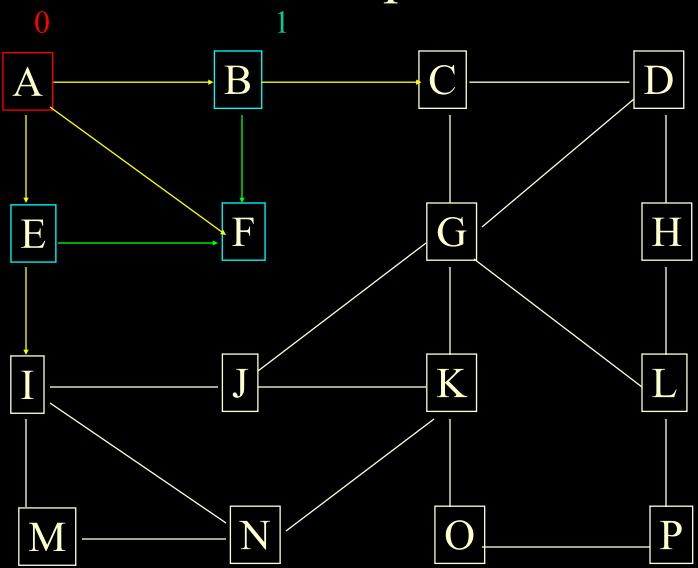
Etc. . . .

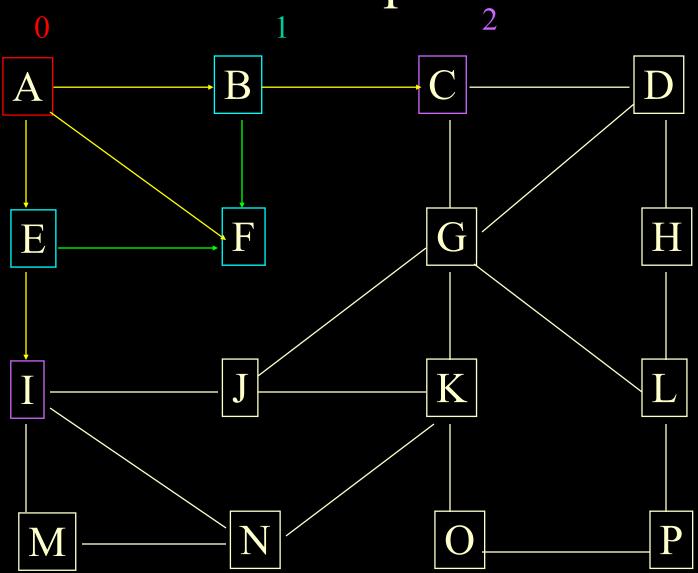


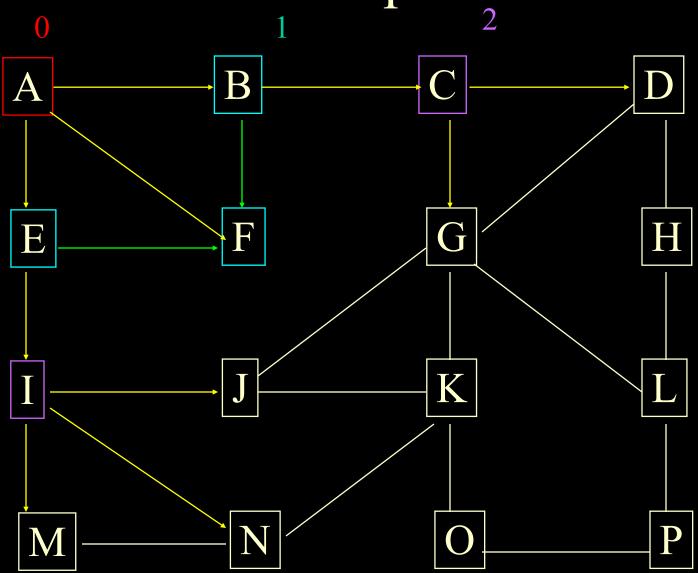


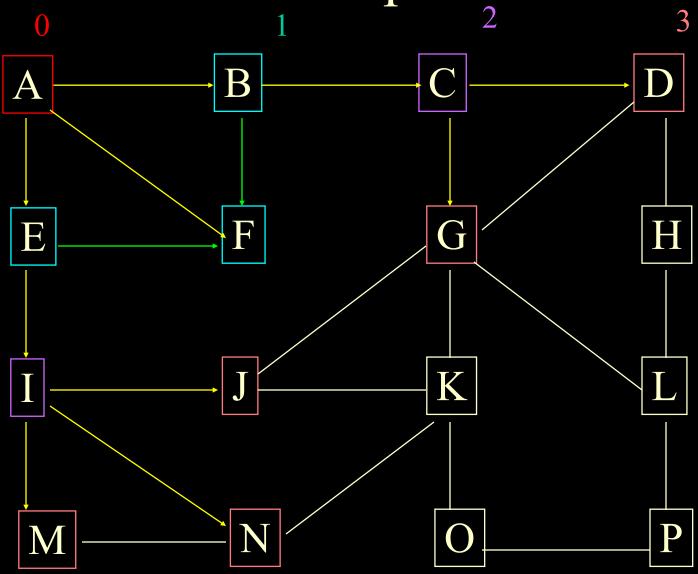


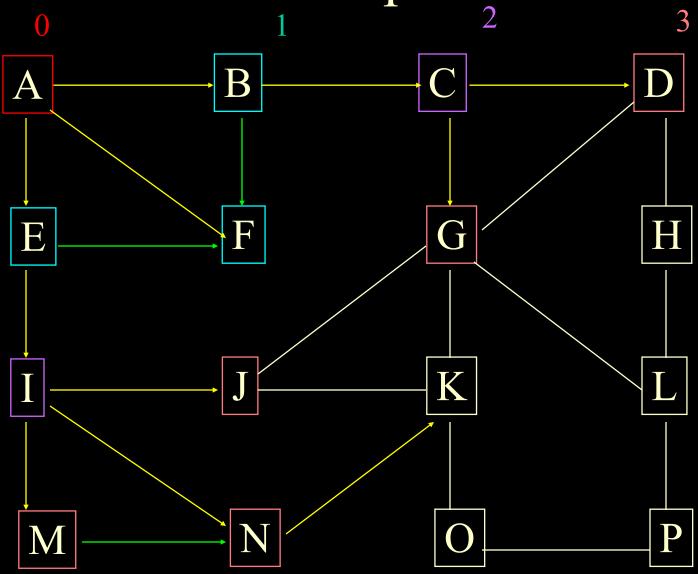


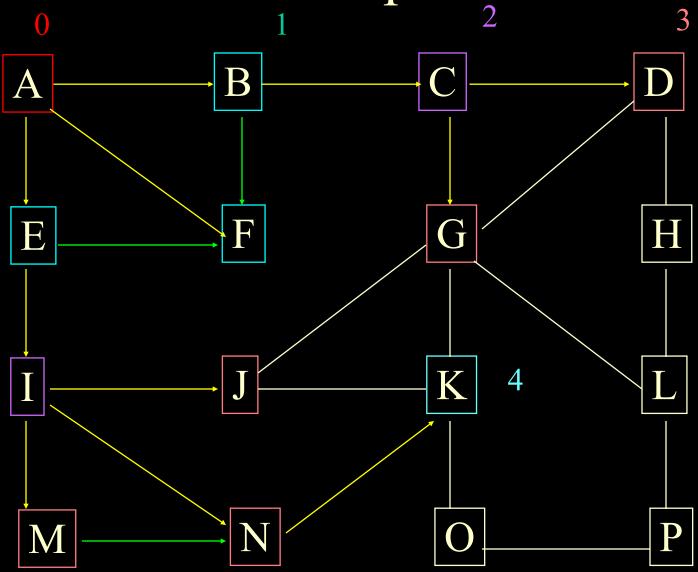


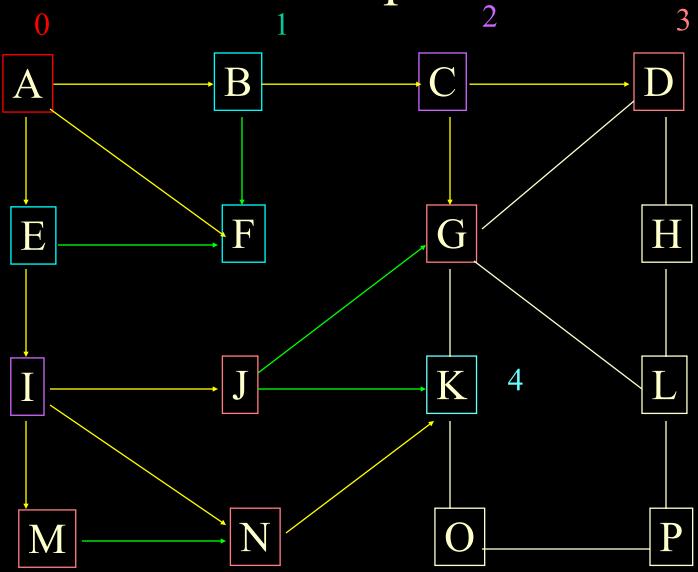


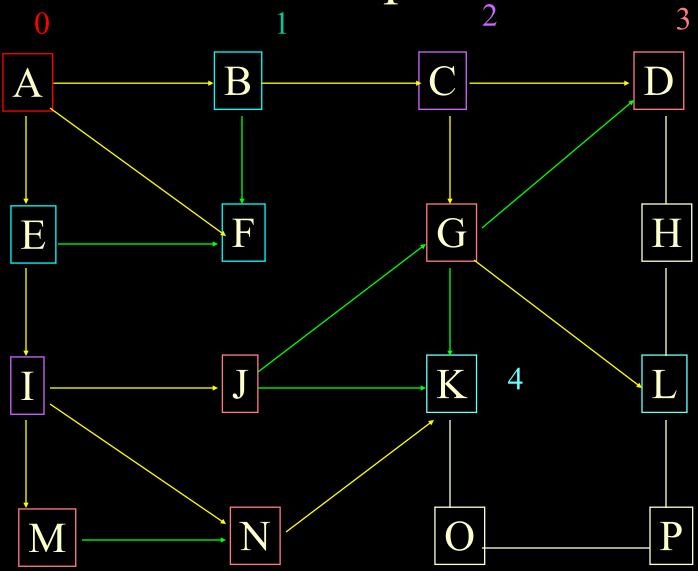


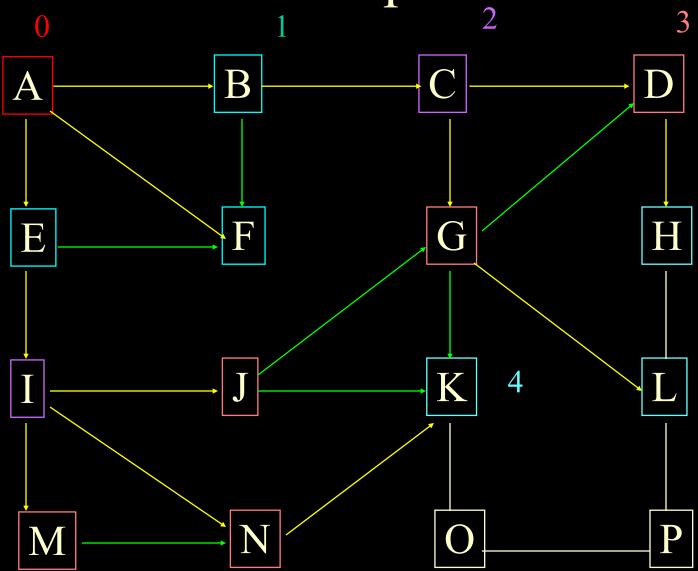


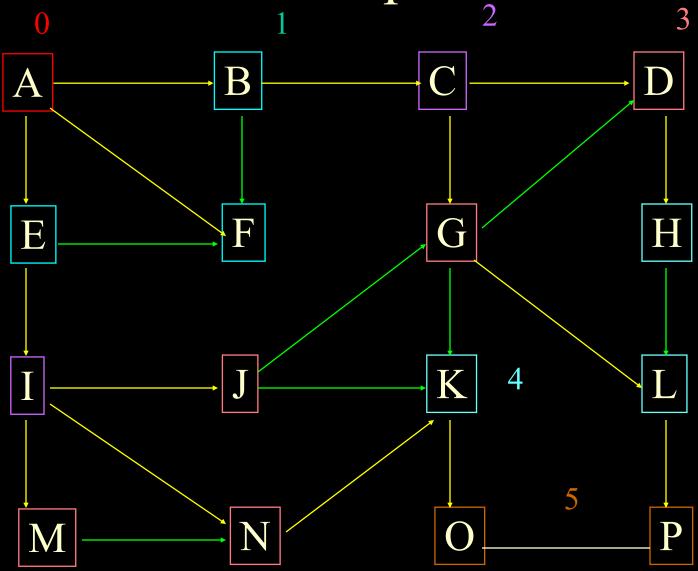


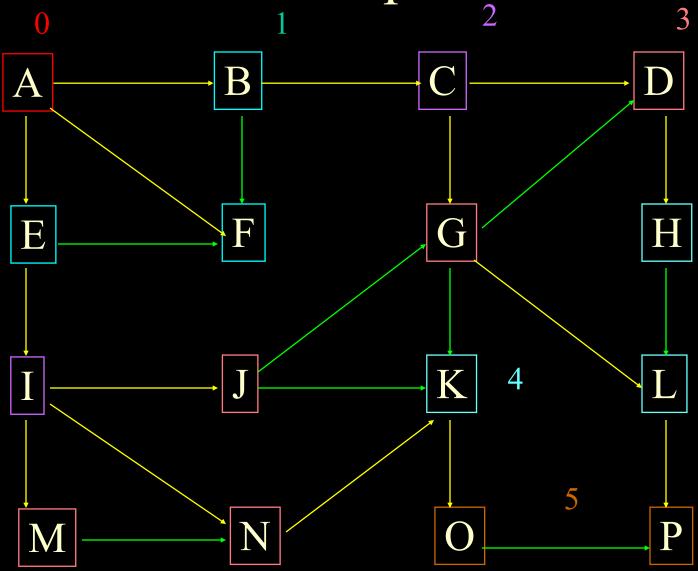




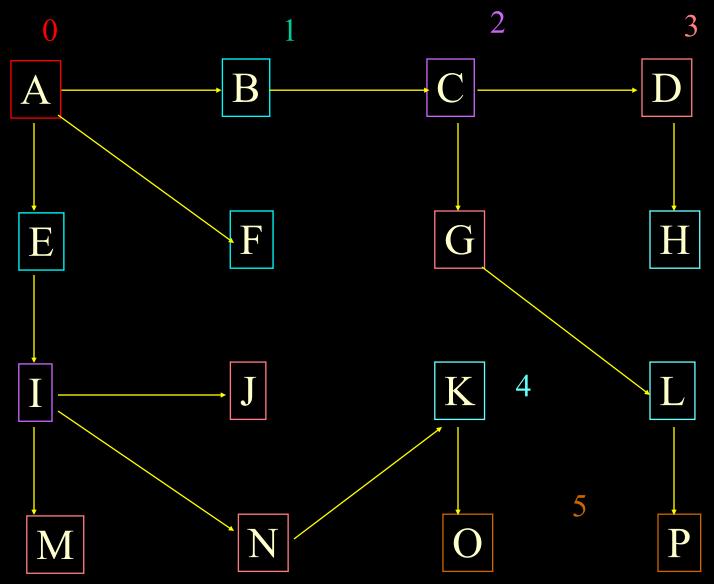








BFS Tree



BFS Pseudocode (1 of 2)

```
BSF(Vertex s)
  initialize container L<sub>0</sub> to contain vertex s
  i \leftarrow 0
  while L<sub>i</sub> is not empty do
       create container L<sub>i+1</sub> to initially be empty
       for each vertex v in L; do
           // next slide
       i \leftarrow i+1
```

BFS Pseudocode (2 of 2)

```
// for each vertex v in L<sub>i</sub> do
  if edge e incident on v do
       let w be the other endpoint of e
      if w is unexplored then
             label e as a discovery edge
             insert w into L<sub>i+1</sub>
       else
             label e as a cross edge
//i \leftarrow i+1
```

BSF Properties

- The traversal visits all vertices in the connected component of s
- The discover edges form a spanning tree of the cc
- For each vertex v at level I, the path of the BSF tree T between s and v has I edges and any other path of G between s and v has at least I edges
- If (u,v) is an edge that is not in the BSF tree, then the level number of u and v differ by at most one

Run Time

A BSF traversal takes O(n+m) time

Also, there exist O(n+m) time algorithms base on BFS which test for

Connectivity of graph

Spanning tree of G

Connected component

Minimum number of edges path between s and v