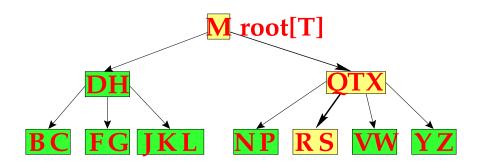
Homework 8 due Tues 11/16

- CLRS 18.1-5 (red-black vs. BTrees)
- CLRS 18.2-6 (complexity in *t*)

Chapter 18: B-Trees

A B-tree is a balanced tree scheme in which balance is achieved by permitting the nodes to have multiple keys and more than two children. **Definition** Let $t \ge 2$ be an integer. A tree T is called a **B-tree** having **minimum degree** t if the leaves of T are at the same depth and each node u has the following properties:

- 1. u has at most 2t 1 keys.
- 2. If u is not the root, u has at least t-1 keys.
- 3. The keys in u are sorted in the increasing order.
- 4. The number of u's children is precisely one more than the number of u's keys.
- 5. For all $i \ge 1$, if u has at least i keys and has children, then every key appearing in the subtree rooted at the i-th child of u is less than the i-th key and every key appearing in the subtree rooted at the (i + 1)-st child of u is greater than the i-th key.



Notation

Let u be a node in a B-tree. By n[u] we denote the number of keys in u. For each i, $1 \le i \le n[u]$, $key_i[u]$ denotes the i-th key of u. For each i, $1 \le i \le n[u] + 1$, $c_i[u]$ denotes the i-th child of u.

Terminology

We say that a node is **full** if it has 2t - 1 keys and we say that a node is **lean** if it has the minimum number of keys, that is t - 1 keys in the case of a non-root and 1 in the case of the root.

2-3-4 Trees

B-trees with maximum degree 2 are called **2-3-4 trees** to signify that the number of children is two, three, or four.

Depth of a B-tree

Theorem A Let $t \ge 2$ and n be integers. Let T be an arbitrary B-tree with minimum degree t having n keys. Let h be the height of T. Then $h \le \log_t \frac{n+1}{2}$.

Proof The height is maximized when all the nodes are lean. If T is of that form, the number of keys in T is

$$1 + \sum_{i=1}^{h} 2(t-1)t^{i-1} = 2(t-1)\frac{t^{h}-1}{t-1} + 1 = 2t^{h}-1.$$

Thus the depth of a B-tree is at most $\frac{1}{\lg t}$ of the depth of an RB-tree.

Searching for a key k in a B-tree

Start with x = root[T].

- 1. If x = nil, then k does not exist.
- 2. Compute the smallest i such that the i-th key at x is greater than or equal to k.
- 3. If the *i*-th key is equal to k, then the search is done.
- 4. Otherwise, set x to the *i*-th child.

The number of examinations of the key is

 $O((2t-1)h) = O(t \log_t (n+1)/2).$

Binary search may improve the search within a node

How do we search for a predecessor?

B-Tree-Predecessor(T, x, i)

1: \triangleright Find a pred. of $key_i[x]$ in T 2: if $i \ge 2$ then 3: if $c_i[x] = \text{nil then return } key_{i-1}[x]$ 4: \triangleright If $i \ge 2 \& x$ is a leaf 5: \triangleright return the (i-1)st key 6: **else** { 7: \triangleright If $i \ge 2 \& x$ is not a leaf 8: \triangleright find the rightmost key in the *i*-th child 9: $y \leftarrow c_i[x]$ repeat 10: 11: $z \leftarrow c_n[y] + 1$ if $z \neq \text{nil}$ then $y \leftarrow z$ 12: until z = nil13: 14: return $key_{n[y]}[y]$ 15: }

```
16: else {

17: \triangleright Find y and j \ge 1 such that

18: \triangleright x is the leftmost key in c_j[y]

19: while y \ne root[T] and c_1[p[y]] = y do

20: y \leftarrow p[y]

21: j \leftarrow 1

22: while c_j[p[y]] \ne y do j \leftarrow j + 1

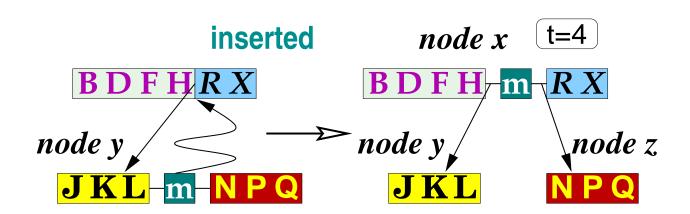
23: if j = 1 then return "No Predecessor"

24: return key_{j-1}[p[y]]

25: }
```

Basic Operations, Split & Merge

Split takes a full node x as part of the input. If x is not the root, then its parent should not be full. The input node is split into three parts: the middle key, a node that has everything to the left of the middle key, and a node that has everything to the right of the middle key. Then the three parts replace the pointer pointing to x. As a result, in the parent node the number of children and the number of keys are both increased by one.



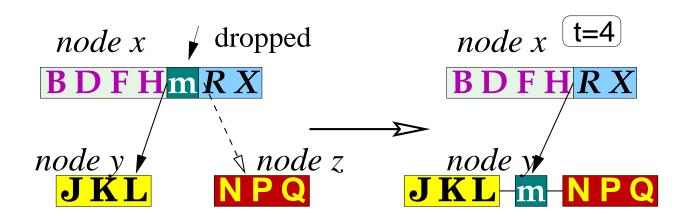
```
B-Tree-Split(T, x)
 1: if n[x] < 2t - 1 then return "Can't Split"
 2: if x \neq root[T] and n[p[x]] = 2t - 1 then
         return "Can't Split"
 3:
 4: \triangleright Create new nodes y and z
 5: n[y] \leftarrow t-1
 6: n[z] \leftarrow t-1
 7: for i \leftarrow 1 to t - 1 do {
 8: key_i[y] \leftarrow key_i[x]
 9: key_i[z] \leftarrow key_{i+t}[x]
10: \}
11: for i \leftarrow 1 to t do {
12: c_i[y] \leftarrow c_i[x]
13:
         c_i[z] \leftarrow c_{i+t}[x]
14: \}
15: \triangleright If x is the root then create a new root
16: if x = root[T] then {
17: \triangleright Create a new node v
18: n[v] \leftarrow 0
19: c_1[v] \leftarrow x
20: p[x] \leftarrow v
21: root[T] \leftarrow v
22: \}
```

23: \triangleright Find the spot for insertion 24: $j \leftarrow 1$ 25: while $c_j[p[x]] \neq x$ do $j \leftarrow j+1$ 26: \triangleright Open up space for insertion 27: if $j \leq n[p[x]]$ then 28: for $i \leftarrow n[p[x]]$ downto j do { $key_{i+1}[p[x]] \leftarrow key_i[p[x]]$ 29: $c_{i+2}[p[x]] \leftarrow c_{i+1}[p[x]]$ 30: 31: } 32: \triangleright Insertion 33: $key_{j}[p[x]] \leftarrow key_{t}[x]$ 34: $c_j[p[x]] \leftarrow y$ 35: $c_{j+1}[p[x]] \leftarrow z$ 36: $n[p[x]] \leftarrow n[p[x]] + 1$ 37: $p[y] \leftarrow p[x]$ 38: $p[z] \leftarrow p[x]$ 39: \triangleright Return the pointer to the parent 40: return p[x]

Merge takes as input a node and the position of a key. Then it merges the key and the pair of children flanking the key into one node.

What kind of properties must the input node and the children satisfy for such an operation be possible? What kind of properties must the input node and the children satisfy for such an operation be possible?

The input node must not be lean, and the two children must be lean.



B-Tree-Merge(T, x, i)1: \triangleright Merge the *i*-th key of x and the two 2: \triangleright children flanking the *i*-th key 3: $y \leftarrow c_i[x]$ \triangleright y is the left child 4: $z \leftarrow c_{i+1}[x]$ $\triangleright z$ is the right child 5: if (n[y] > t - 1 or n[z]] > t - 1) then 6: return "Can't Merge" 7: $key_t[y] \leftarrow key_i[x]$ \triangleright Append the middle key 8: for $j \leftarrow 1$ to t - 1 do \triangleright Copy keys from z $key_{t+j}[y] \leftarrow key_j[z]$ 9: 10: for $j \leftarrow 1$ to t do { 11: $c_{t+j}[y] \leftarrow c_j[z]$ \triangleright Copy children from z $p[c_j[z]] \leftarrow y$ 12: \triangleright Fix the parent pointers 13: } 14: $n[x] \leftarrow n[x] - 1$ \triangleright Fix the *n*-tag 15: if (n[x] = 0) then $\{ > \text{ If } x \text{ was the root} \}$ 16: $root[T] \leftarrow y$ \triangleright and was lean, then 17: $p[y] \leftarrow \text{nil}$ \triangleright y becomes the root 18: }

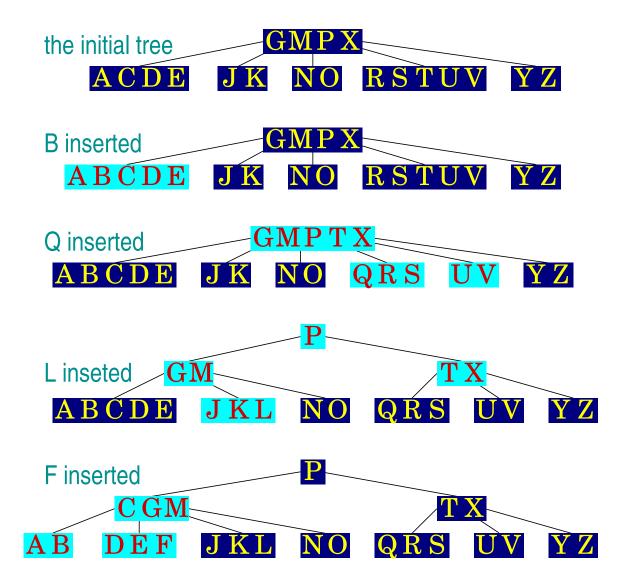
19: \triangleright If the middle key is not the last key 20: \triangleright Fill the gap by moving things 21: else if $i \le n[x]$ then { 21: for $j \leftarrow i$ to n[x] do 22: $key_j[x] \leftarrow key_{j+1}[x]$ 23: for $j \leftarrow i$ to n[x] do 24: $c_j[x] \leftarrow c_{j+1}[x]$ 25: }

Insertion of a key

Suppose that a key k needs to be inserted in the subtree rooted at y in a B-tree T.

Before inserting the key we make sure that is room for insertion, that is, not all the nodes in the subtree are full. Since visiting all the nodes in the subtree is very costly, we will make sure only that y is not full.

If y is a leaf, insert the key. If not, find a child in which the key should go to and then make a recursive call with y set to the child.



```
B-Tree-Insert(T, y, k)
 1: z \leftarrow y
 2: f \leftarrow false
 3: while f = false do \{
         if n[z] = 2t - 1 then
 3:
 4: z \leftarrow \text{B-Tree-Split}(T, z)
 5: j \leftarrow 1
 6: while key_j[z] < k and j \le n[z] do
 7:
             j \leftarrow j + 1
 8: if c_j[z] \neq \text{nil then } z \leftarrow c_j[z]
 9: else f \leftarrow true
10: \}
11: for i \leftarrow n[z] downto j do
     key_{j+1}[z] \leftarrow key_j[z]
12:
13: key_i \leftarrow k
14: n[z] \leftarrow n[z] + 1
15: return z
```

<u>Deletion</u>

The task is to receive a key k and a B-tree T as input and eliminate it from T if it is in the tree. To accomplish this, we will take an approach similar to that we took for binary search trees.

- Search for k. If the node containing k is a leaf, eliminate k.
- Otherwise, search for the predecessor k in the subtree immediate to the right of k. Relocate the predecessor to the position of k.

What should we be careful about?

We should avoid removing a key from a lean leaf.

To avoid such a case, we can take a strategy similar to that we took in Insertion, that is, when a node is about to be visited, make sure that the node is not lean.

Strategy

When a lean node x is about to be visited, do the following:

- In the case when x is not the first child, if its immediate left sibling is not lean move the last key and the last child of the sibling to x; otherwise merge the sibling, x, and the key between them into one.
- In the case when x is the first child, if its immediate right sibling is not lean move the first key and the first child of the sibling to x; otherwise merge the sibling, x, and the key between them into one.

We can then assume that if x is not the root then its parent is not lean.

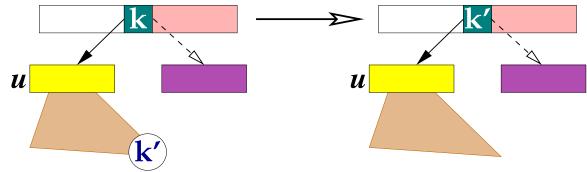
As we go down the tree, at each level there are three cases:

- 1. found k, this is a leaf
- 2. found k, this is not a leaf
- 3. did not find k

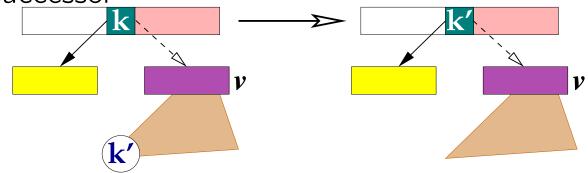


Case 2: k is in an internal node:

2a: left child has at least t nodes: take predecessor

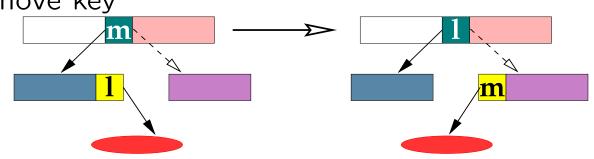


2a: right child has at least t nodes: take successor



Case 3: not found yet: find subtree containing k

Case 3a: either sibling has at least t keys: move key



Case 3b: both siblings lean: merge with one sibling

