

# **CSC 252: Computer Organization**

## **Fall 2021: Lecture 17**

The Storage Hierarchy, continued

Instructor: Alan Beadle

Department of Computer Science  
University of Rochester

# Announcements

Midterm solutions will be posted soon

To view your midterm, come to office hours or make an appointment.

Grading errors must be brought up before leaving with your exam for integrity reasons.

A4 will be out on Wednesday

# NVMEM

Non-volatile memory

Higher density than DRAM

A bit slower, but DRAM scaling is hitting some limits

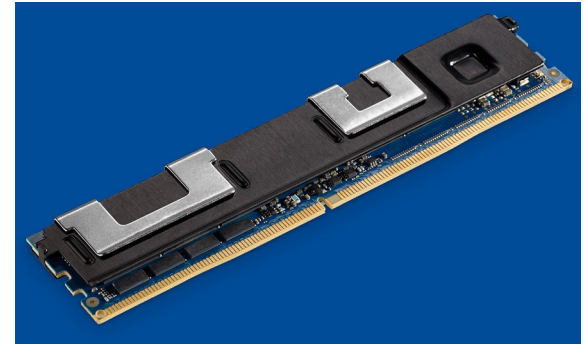
Server applications demand more memory, NVMEM can provide it

Just like volatile memory, there are many different ways to build it

# NVMEM: Intel Optane

AKA “3D Xpoint” memory

Currently available



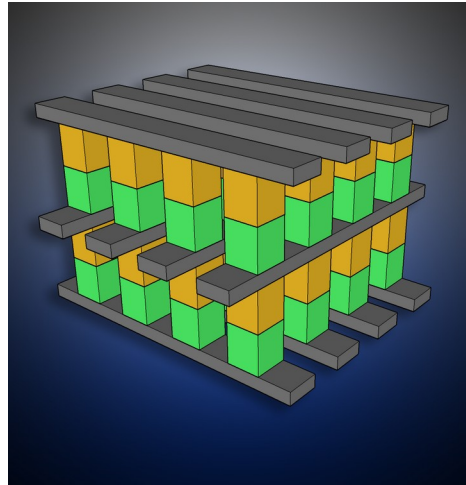
Fits in a DIMM slot, looks like a normal RAM stick

Supported by high-end Intel Xeon CPUs (mostly servers)

Can support huge memory capacities compared to DRAM (hundreds of gigabytes, up to terabytes)

# NVMEM: Intel Optane

Optane is built using a technique known as “Resistive RAM” (ReRAM)



Bits are stored as an electrical resistance in material

An electrical signal can cause the material to become high resistance or low resistance, and it doesn't need to be refreshed.

# Using Optane

Although you can just start using it like we have been using DRAM, that might not be optimal!

With more memory, software design priorities can change

Also, since it is “persistent”, some data can stay in memory instead of a hard drive or SSD

Except we need to design software to do that now! This can be tricky

# Using Optane

Although Optane is nonvolatile, the CPU registers and cache are still volatile

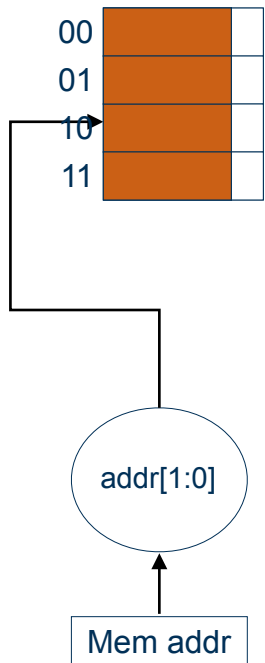
Cache has been designed so that the programmer doesn't have to worry about it much, but this becomes a problem when you actually care if data is in cache or in memory!

This makes it more complicated to know if something is fully persisted/saved

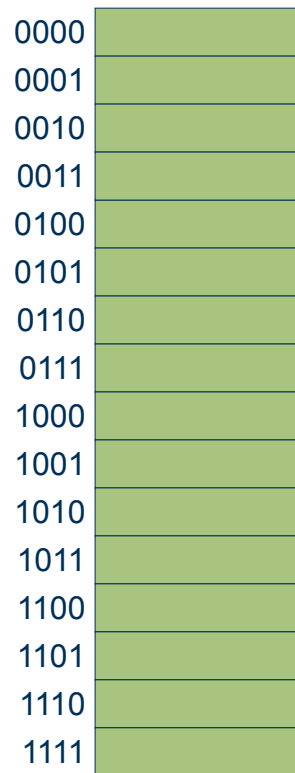
Lots of research opportunities

# Direct-Mapped Cache

Cache



Memory



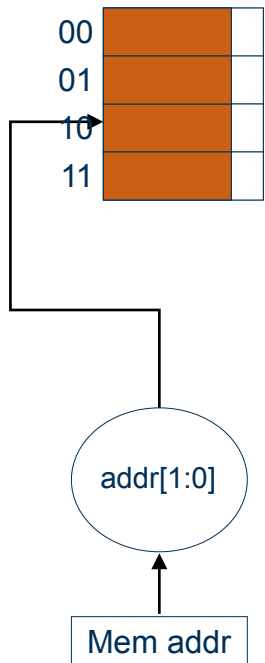
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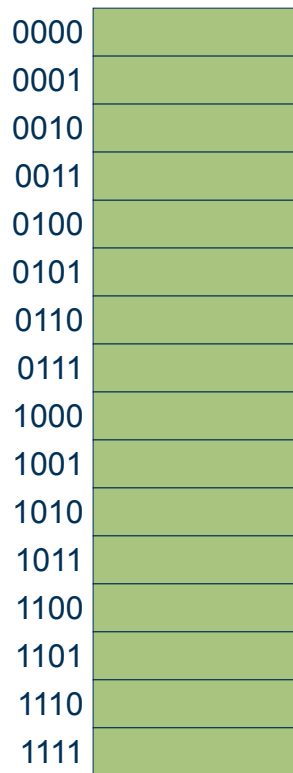


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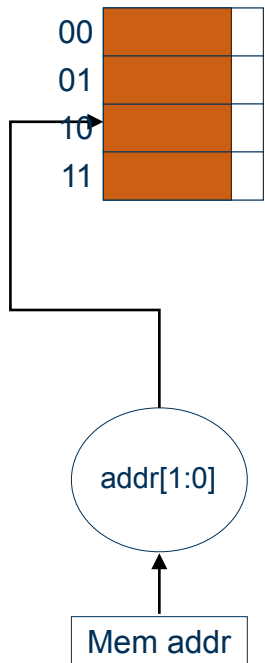
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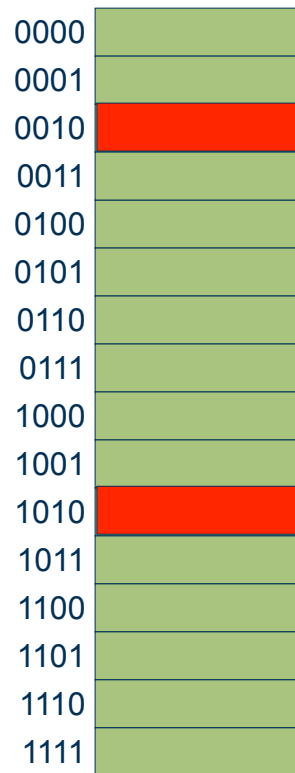
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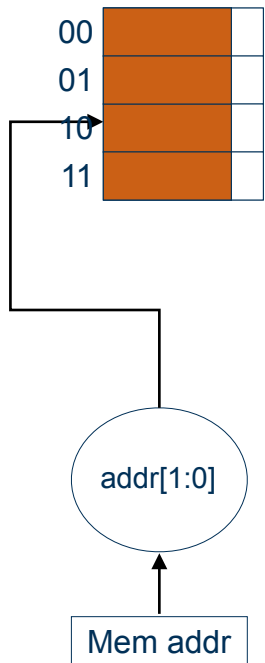
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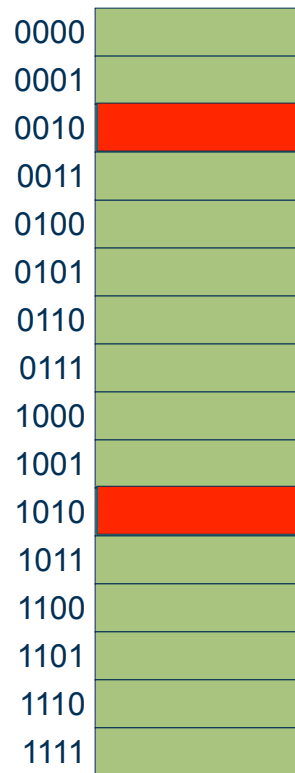
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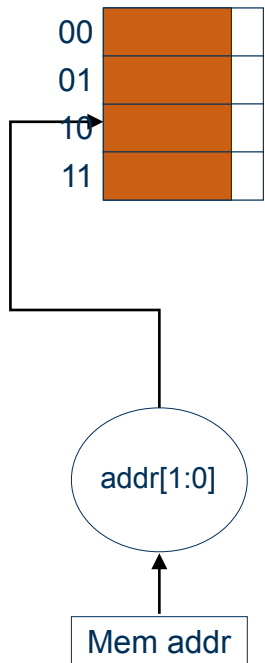
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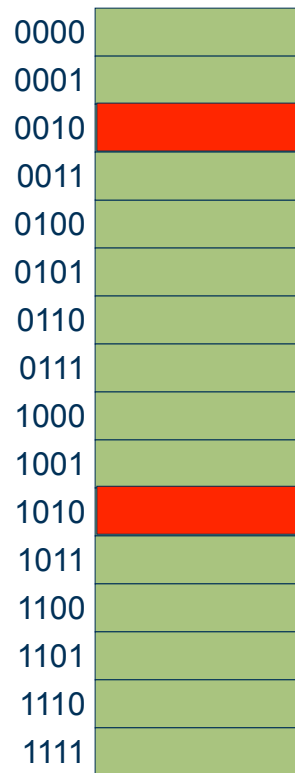
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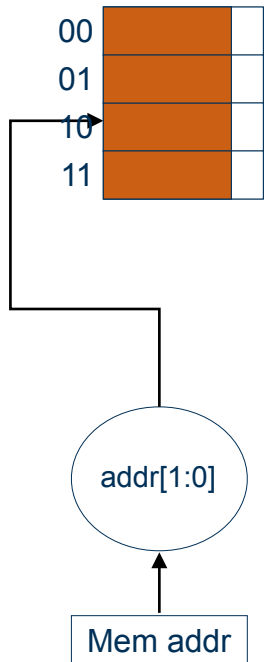
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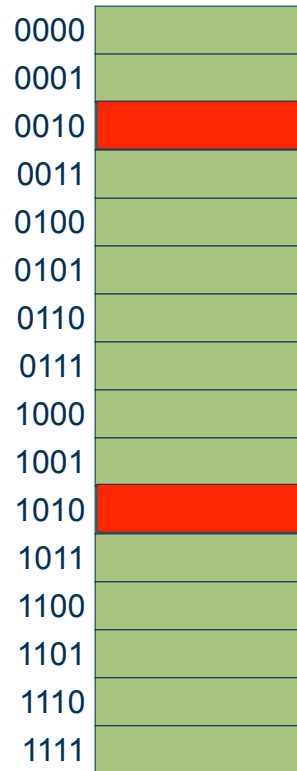
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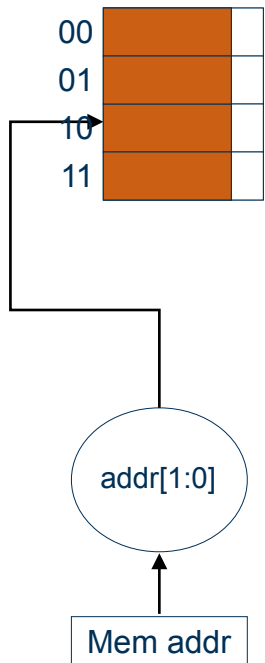
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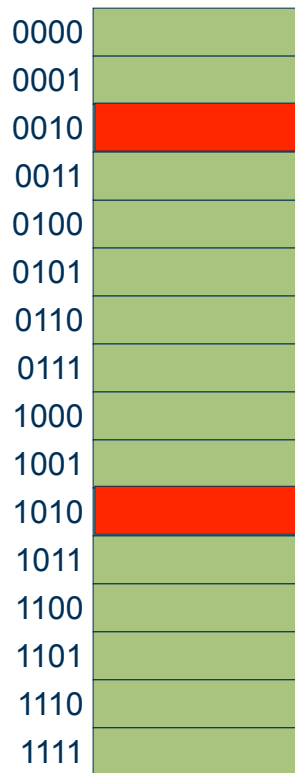
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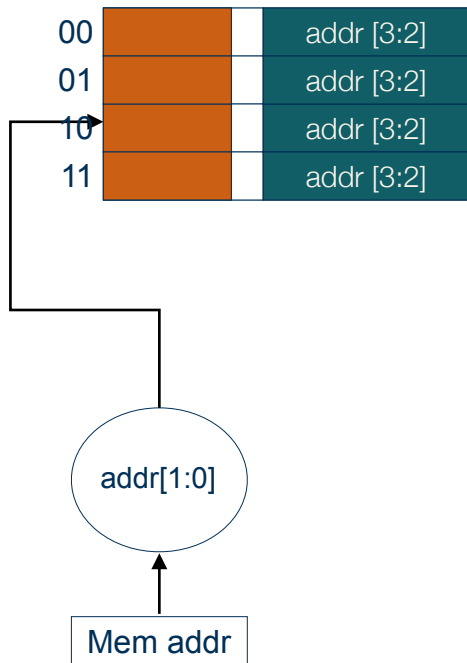
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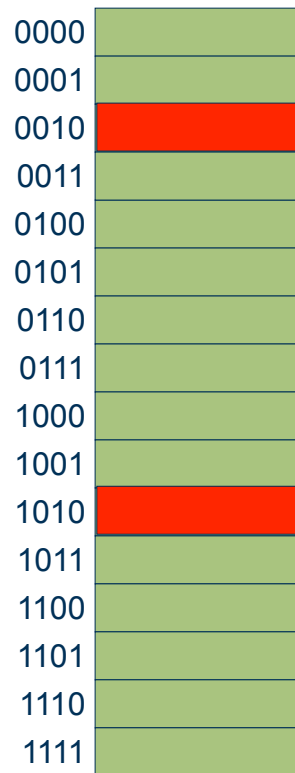
- Add a tag field for that purpose
- What should the tag field be?
- ADDR[3] and ADDR[2] in this particular example

# Direct-Mapped Cache

## Cache



## Memory



## • Direct-Mapped Cache

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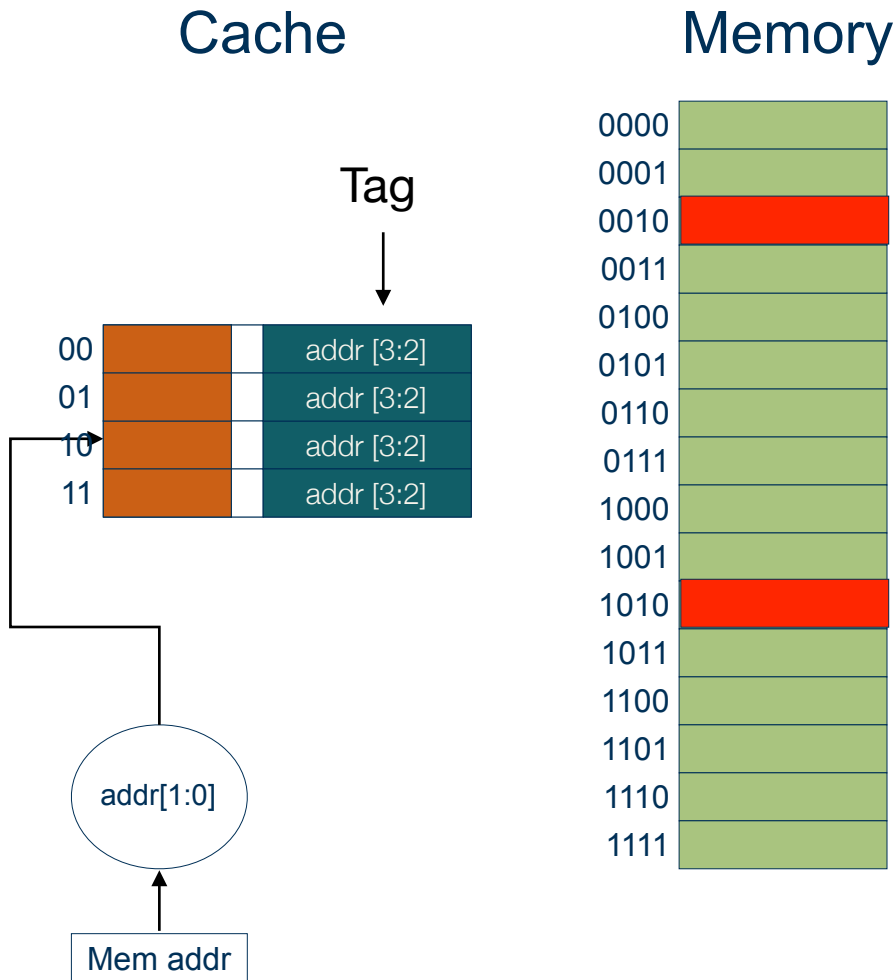
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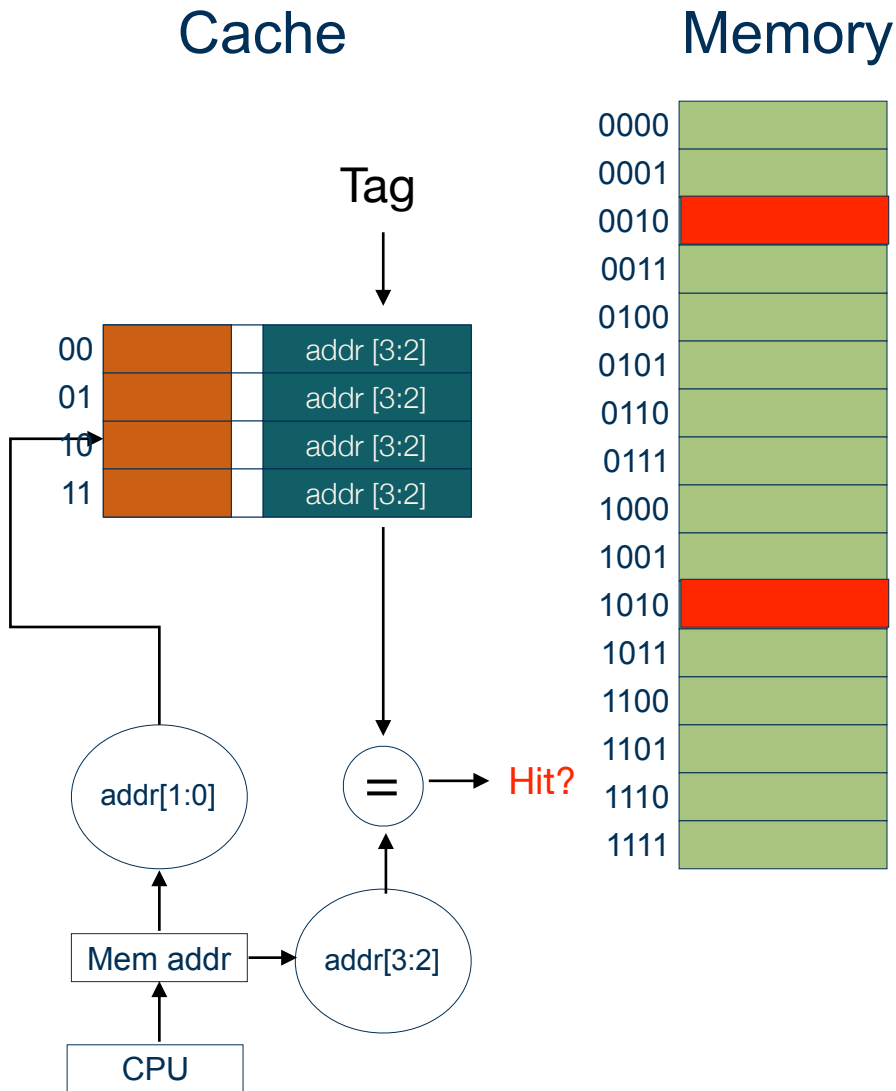
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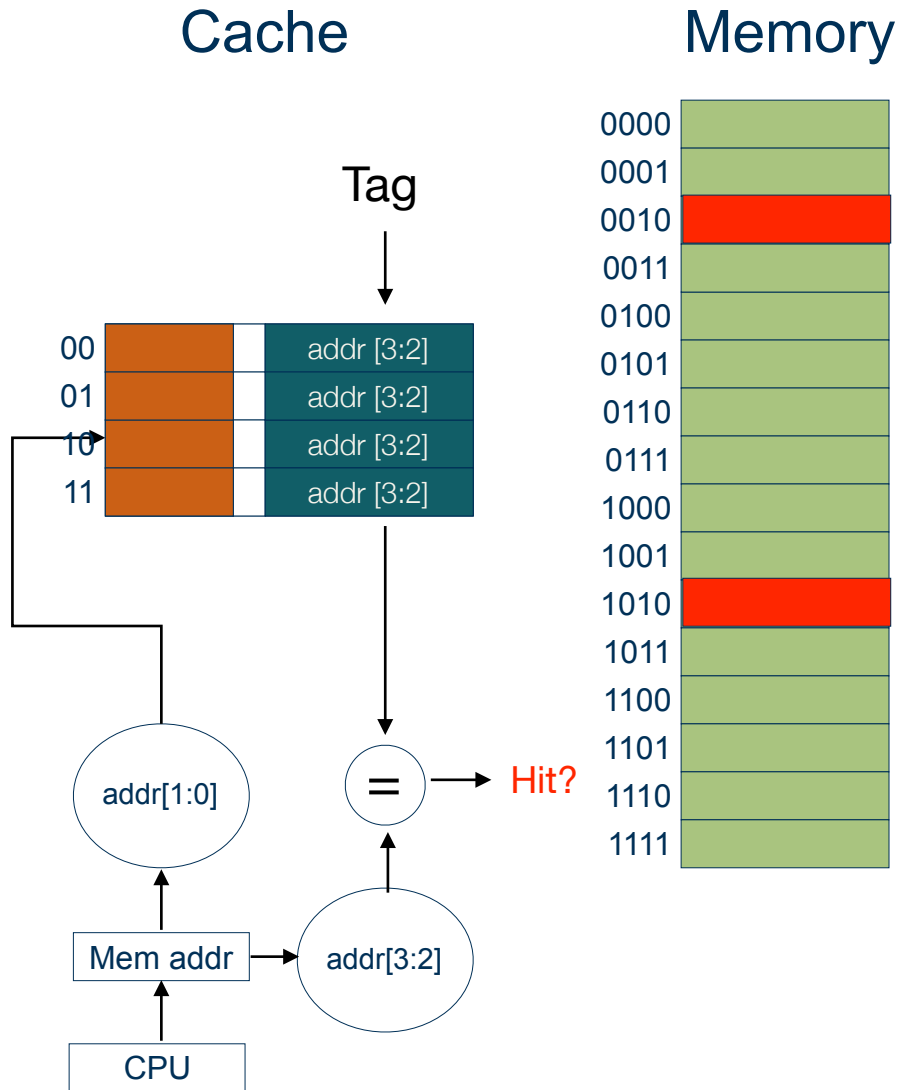


# Direct-Mapped Cache



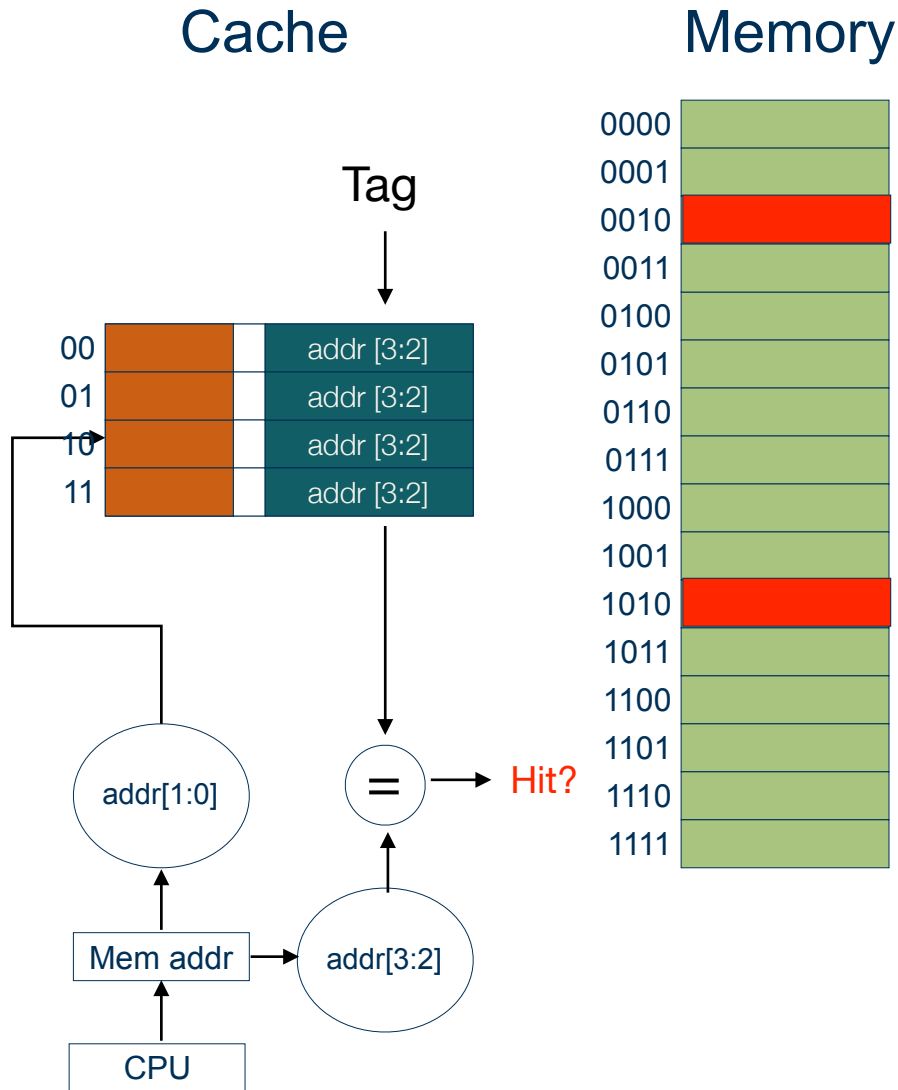
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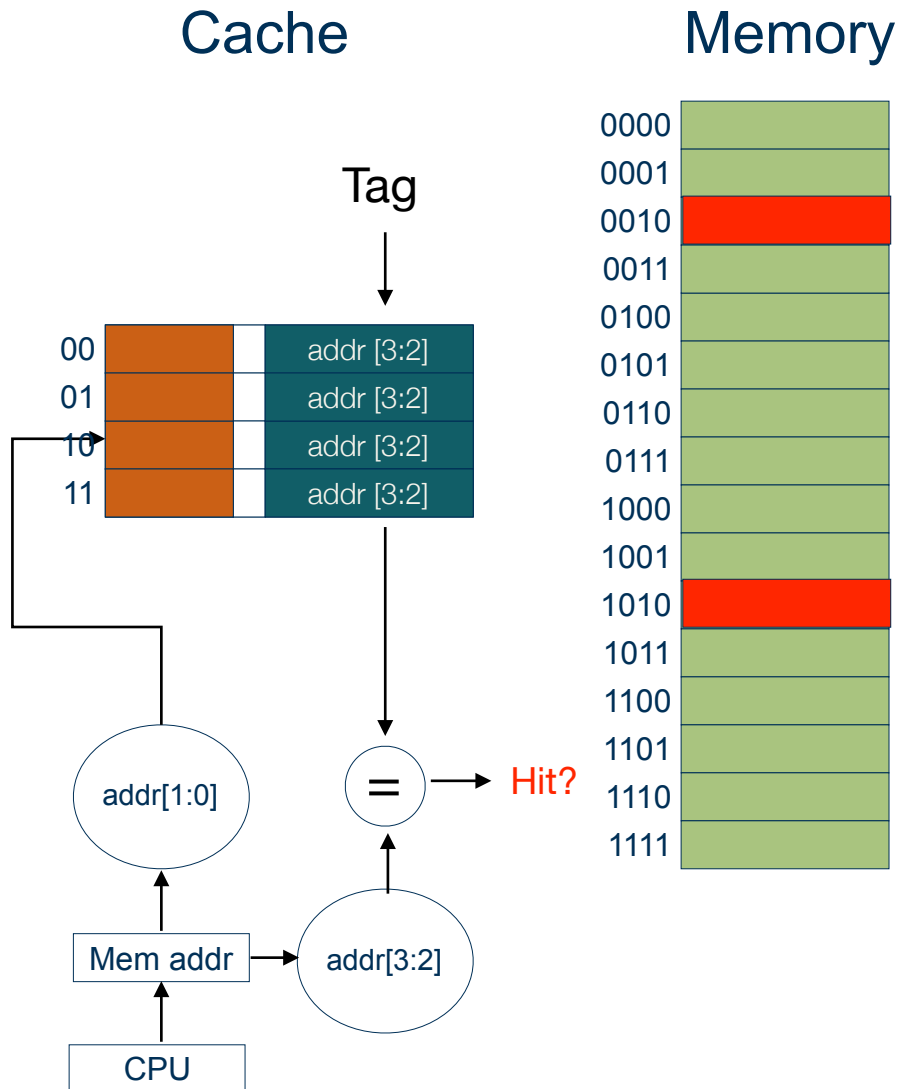
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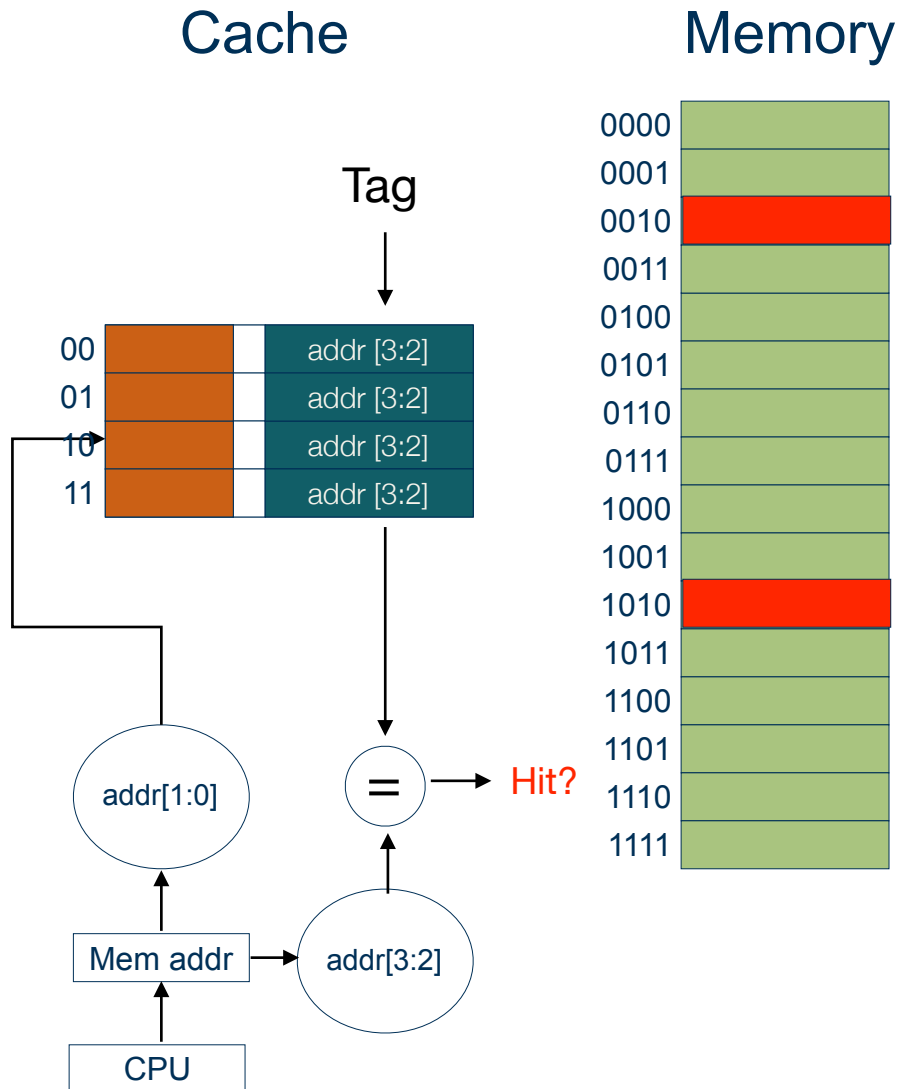
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- How do we improve this?

# Direct-Mapped Cache



- Limitation: each memory location can be mapped to only one cache location.
- This leads to a lot of conflicts.
- How do we improve this?
- Can each memory location have the flexibility to be mapped to different cache locations?

# Fully Associative Cache



Content Valid? Tag

- Every memory location can be mapped to any cache line in the cache.

0000	
0001	
0010	
0011	
0100	
0101	
0110	
0111	
1000	0xEF
1001	0xAC
1010	0x06
1011	
1100	
1101	0x70
1110	
1111	

# Fully Associative Cache



Content Valid? Tag

- Every memory location can be mapped to any cache line in the cache.
- Given a request to address A from the CPU, detecting cache hit/miss requires:
  - Comparing address A with all four tags in the cache (a.k.a., associative search)

0000	
0001	
0010	
0011	
0100	
0101	
0110	
0111	
1000	0xEF
1001	0xAC
1010	0x06
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1111	

# A Few Terminologies



Content Valid? Tag

- A cache line: content + valid bit + tag bits
  - Valid bit + tag bits are “overhead”
  - Content is what you really want to store
  - But we need valid and tag bits to correctly access the cache

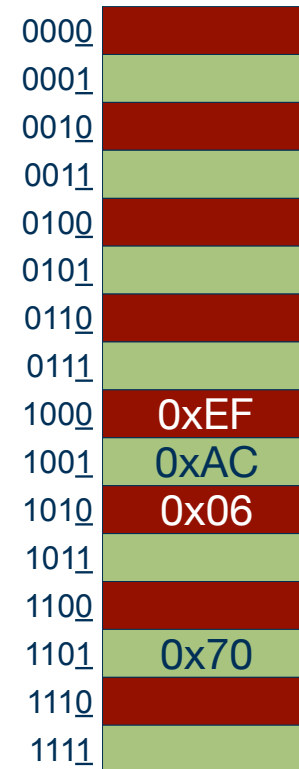
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# A Middle Ground: 2-Way Associative Cache



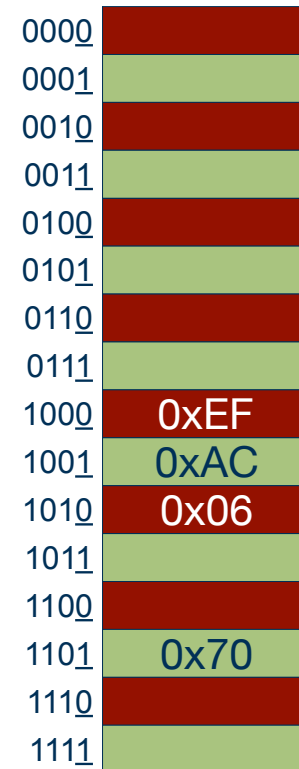
- 4 cache lines are organized into two sets; each set has 2 cache lines (i.e., 2 ways)



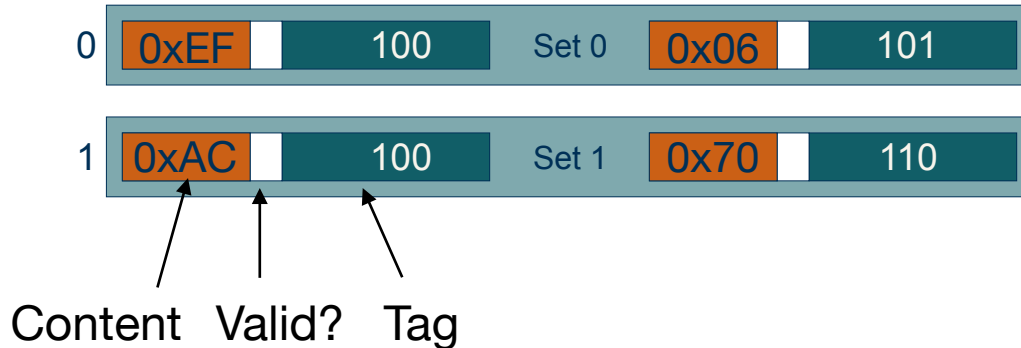
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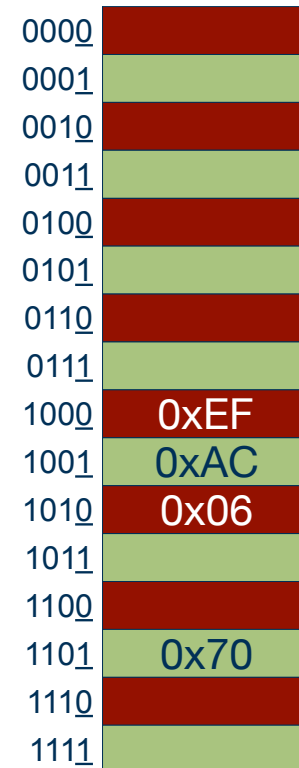
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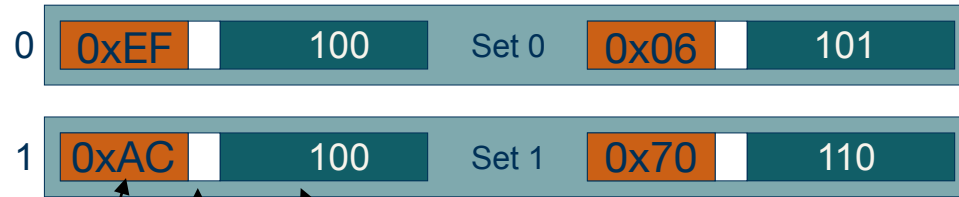
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- 4 cache lines are organized into two sets; each set has 2 cache lines (i.e., 2 ways)
- Even address go to first set and odd addresses go to the second set
- Each address can be mapped to either cache line in the same set
  - Using the LSB to find the set (i.e., odd vs. even)
  - Tag now stores the higher 3 bits instead of the entire address

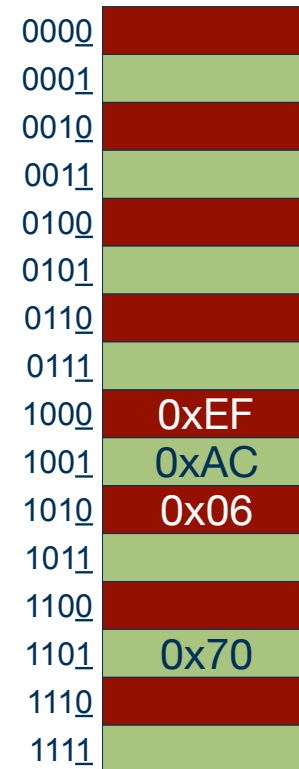


# 2-Way Associative Cache

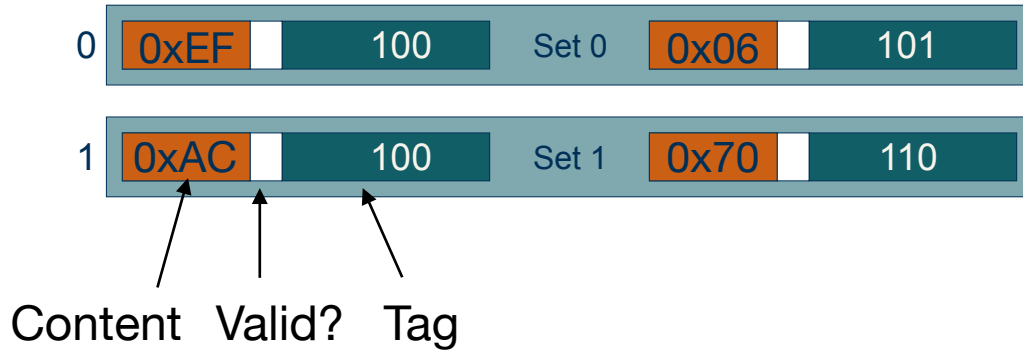


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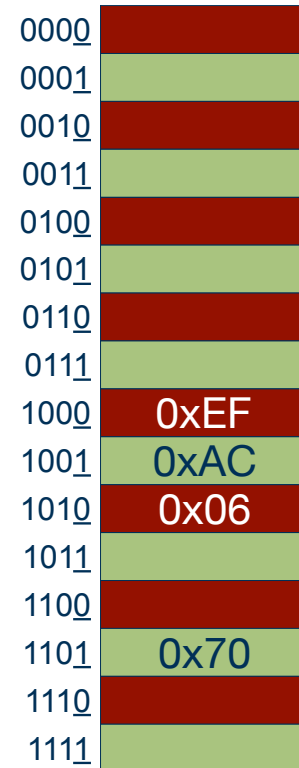
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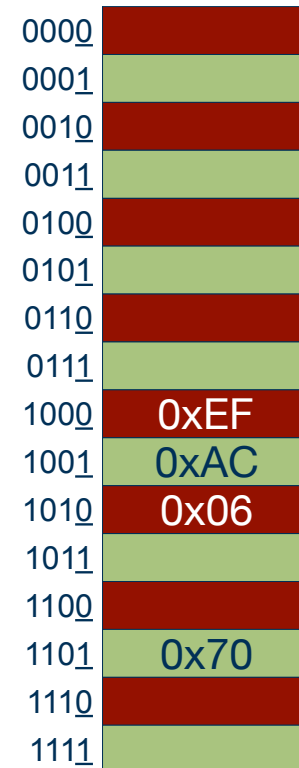
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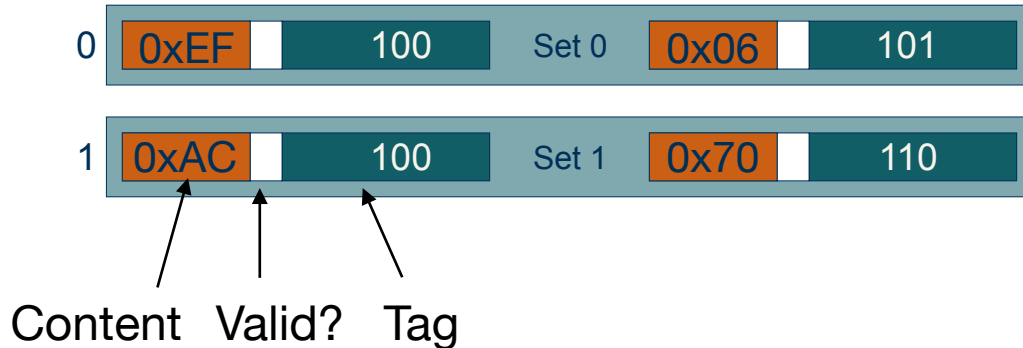
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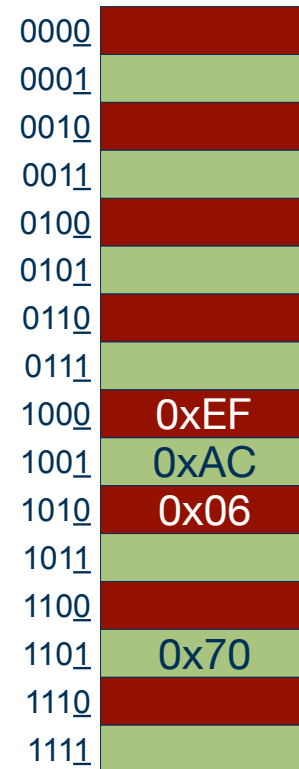
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  - Only two comparisons required



# Direct-Mapped (1-way Associative) Cache

00	0xEF		10
01	0xAC		10
10	0x06		10
11			

Content Valid? Tag

- 4 cache lines are organized into four sets
- Each memory localization can only be mapped to one set
  - Using the 2 LSBs to find the set
  - Tag now stores the higher 2 bits

0000	
0001	
0010	
0011	
0100	
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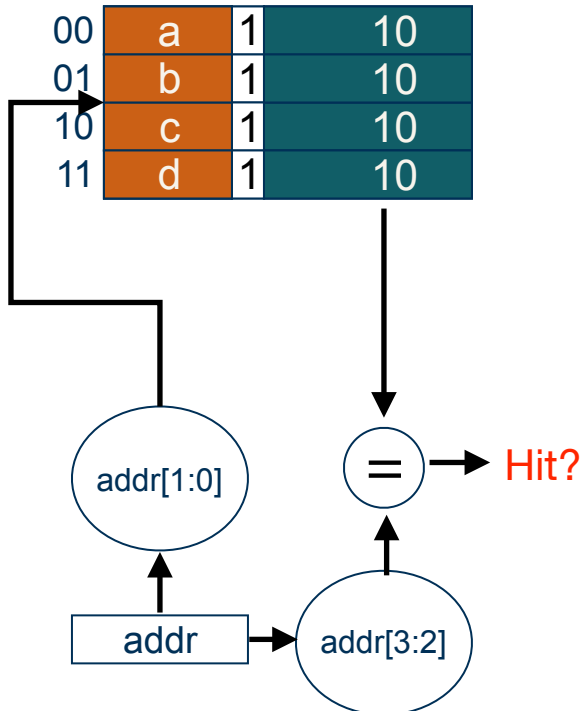
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- Direct-Mapped cache
  - Generally lower hit rate
  - Simpler, Faster

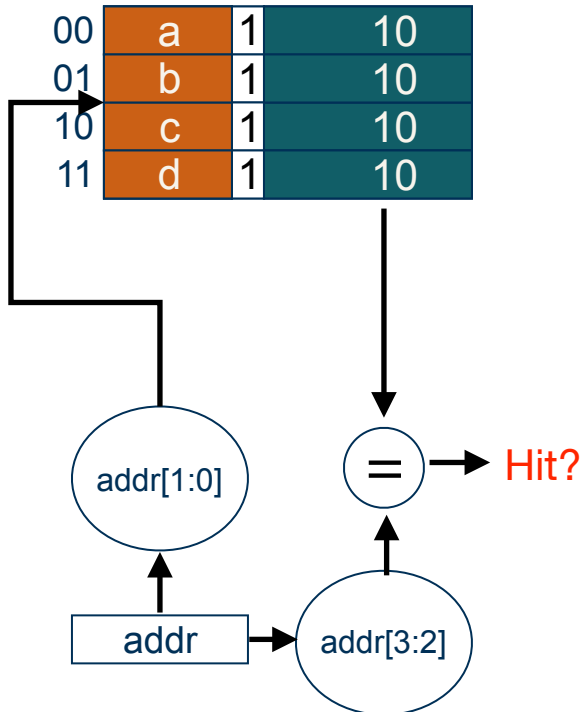
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  - Slower and higher power consumption. Why?

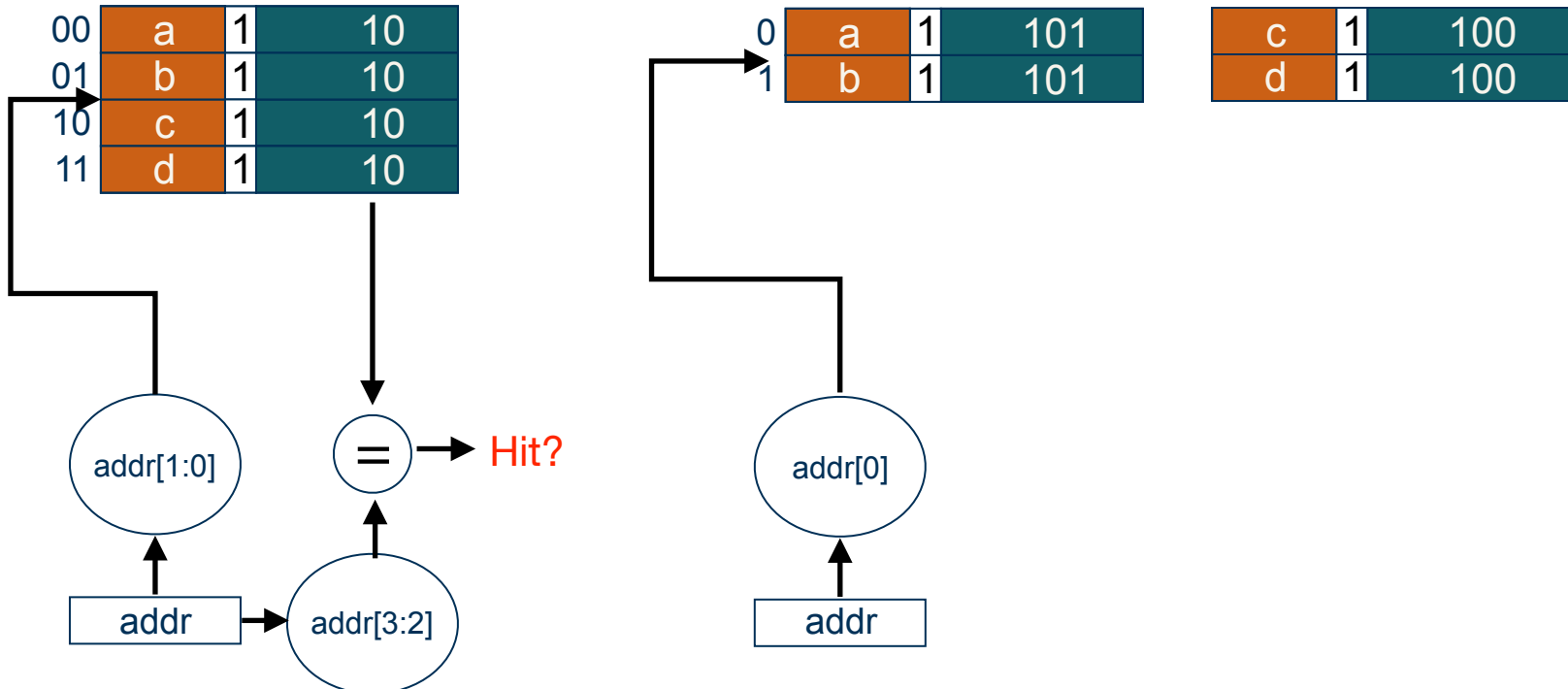


0	a	1	101
1	b	1	101

	c	1	100
	d	1	100

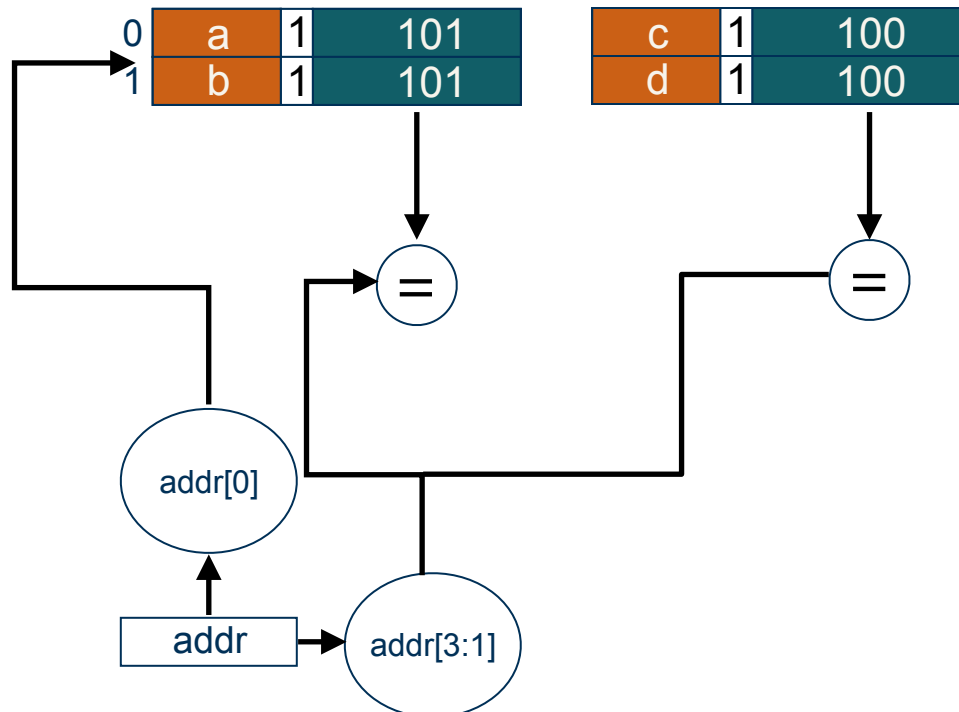
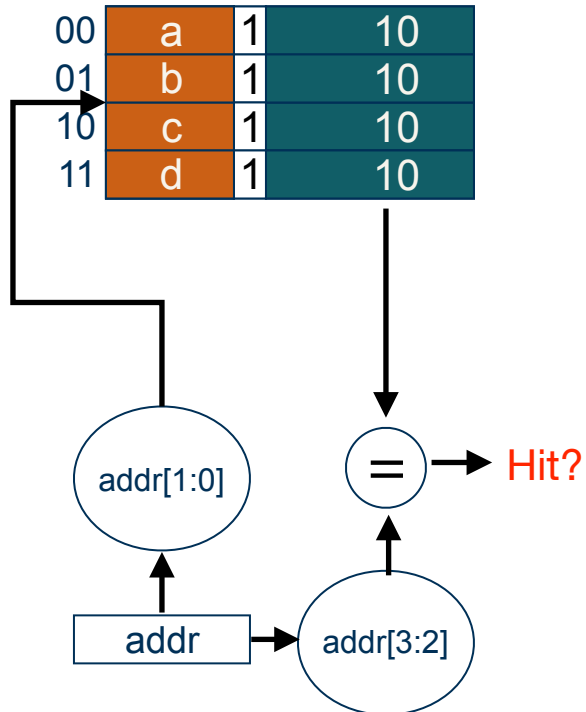
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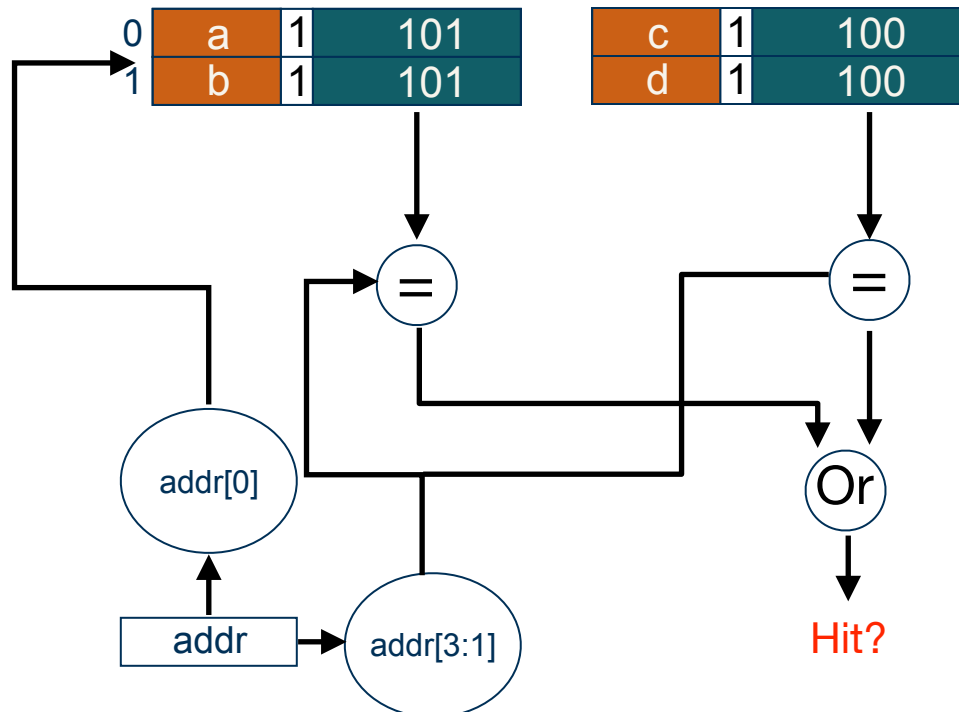
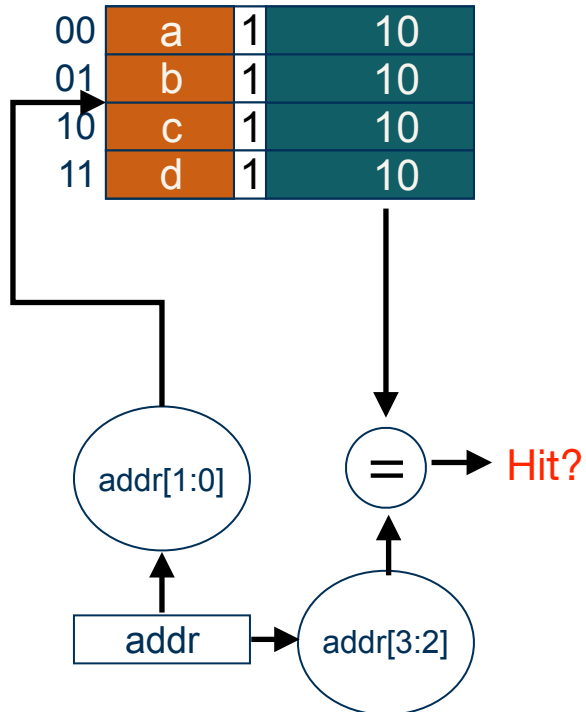
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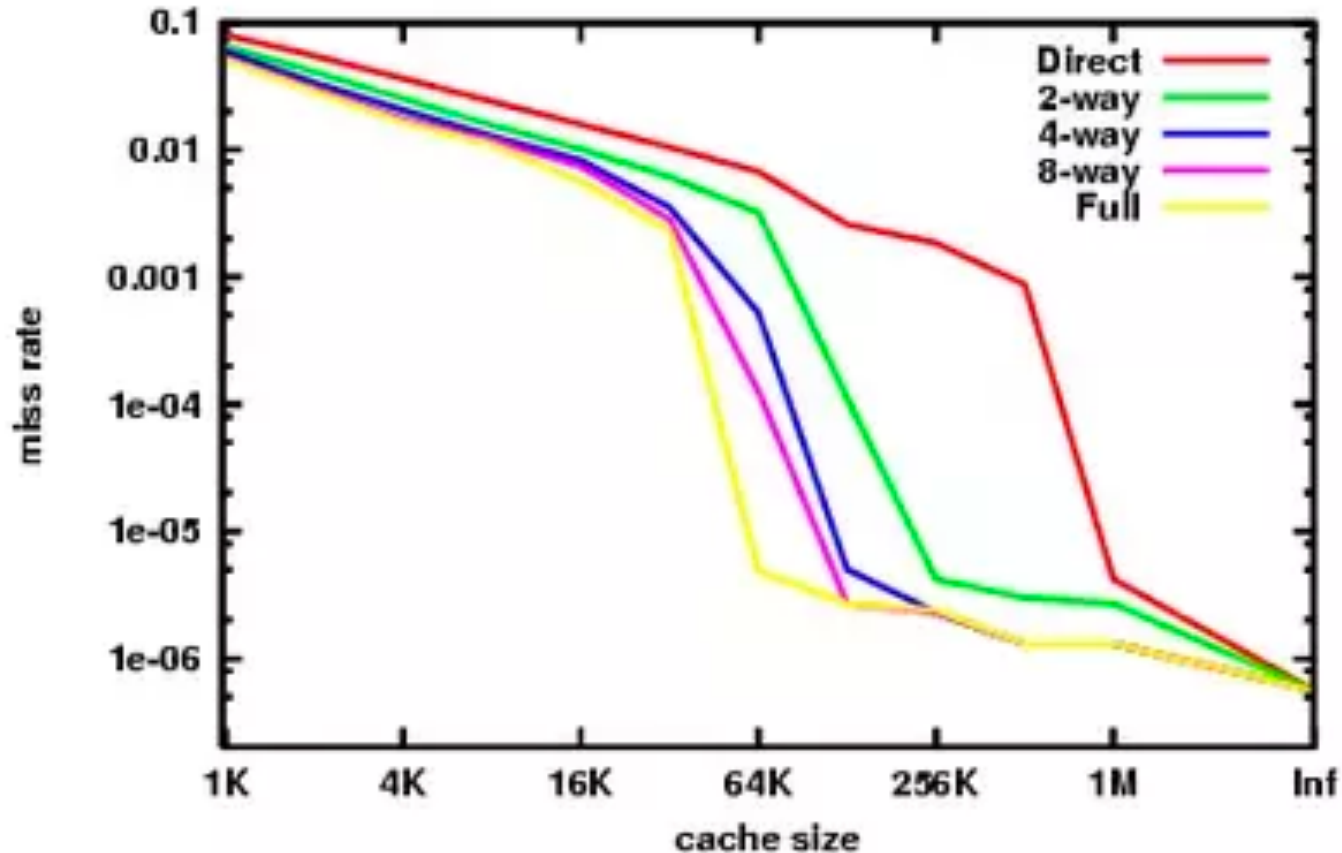


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# Associative versus Direct Mapped Trade-offs



Miss rate versus cache size on the Integer portion of SPEC CPU2000



# Cache Organization

- Finding a name in a roster
- If the roster is completely unorganized
  - Need to compare the name with all the names in the roster
  - Same as a fully-associative cache
- If the roster is ordered by last name, and within the same last name different first names are unordered
  - First find the last name group
  - Then compare the first name with all the first names in the same group
  - Same as a set-associative cache

# Cache Access Summary (So far...)

- Assuming  $b$  bits in a memory address
- The  $b$  bits are split into two halves:
  - Lower  $s$  bits used as index to find a set. Total sets  $S = 2^s$
  - The higher  $(b - s)$  bits are used for the tag
- Associativity  $n$  (i.e., the number of ways in a cache set) is **independent** of the the split between index and tag

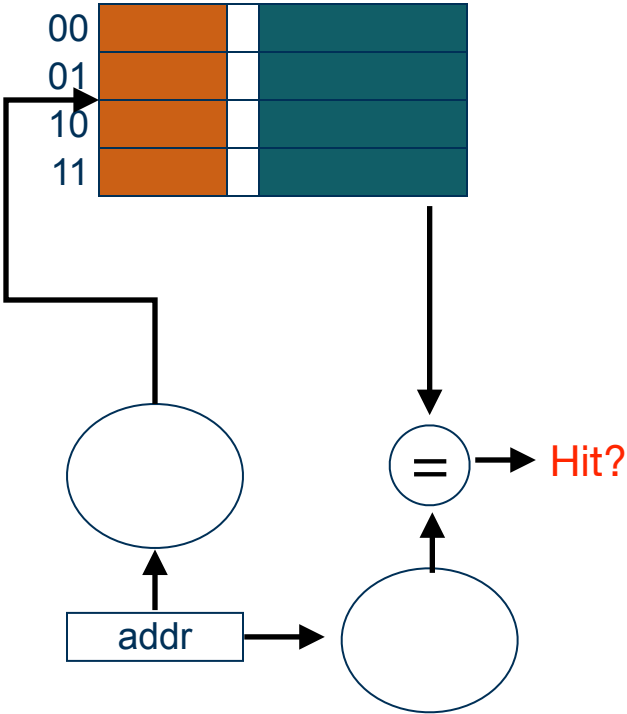


# Locality again

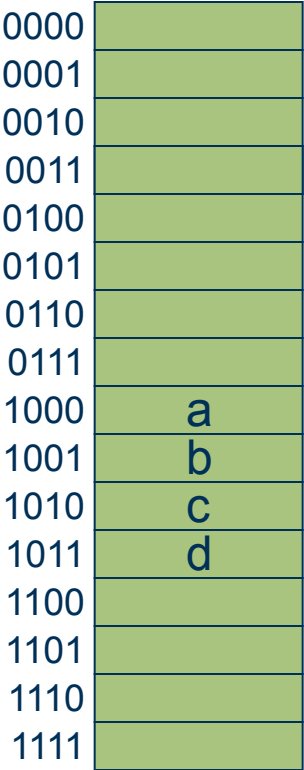
- So far: temporal locality
- What about spatial?
- Idea: Each cache location (cache line) store multiple bytes

# Cache-Line Size of 2

Cache

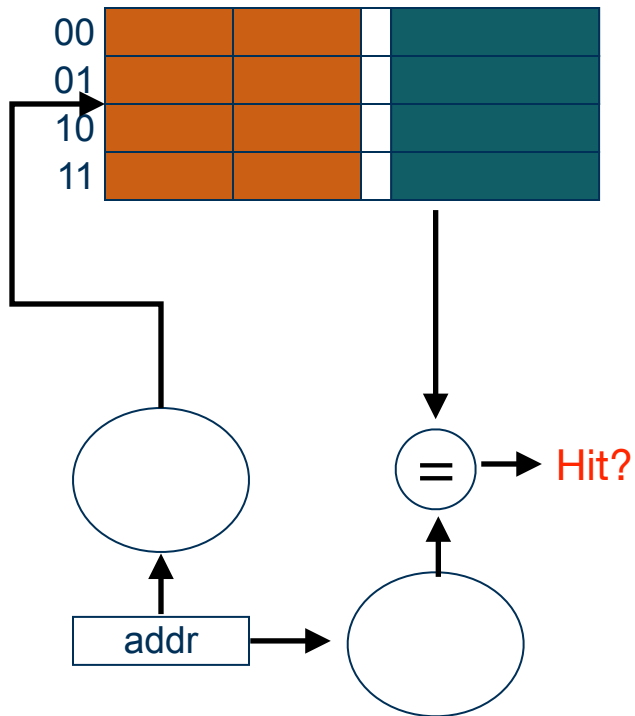


Memory

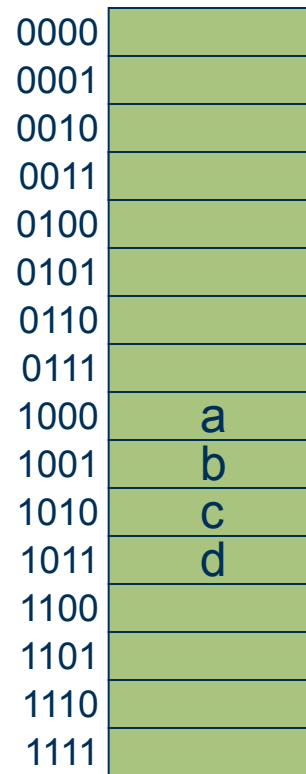


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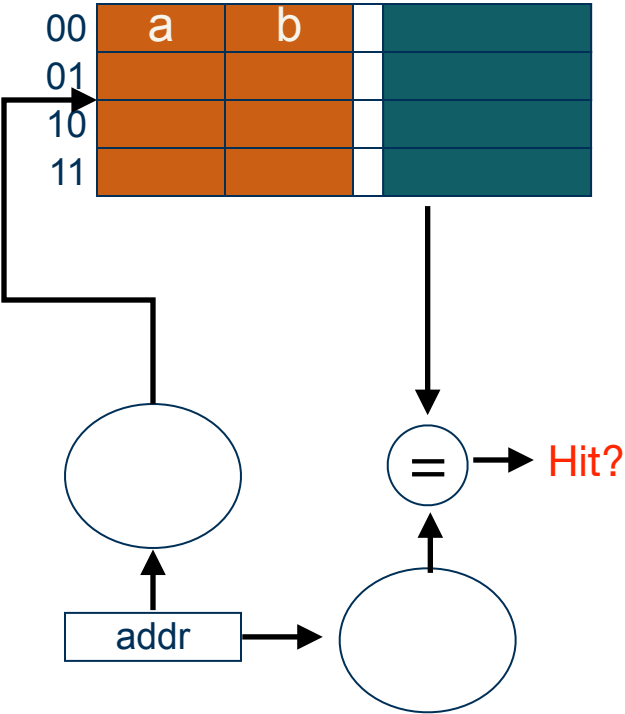


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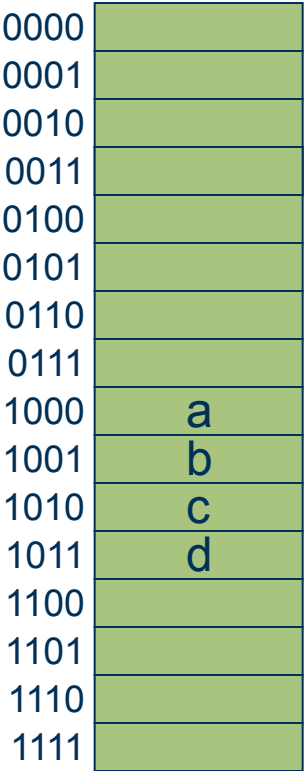


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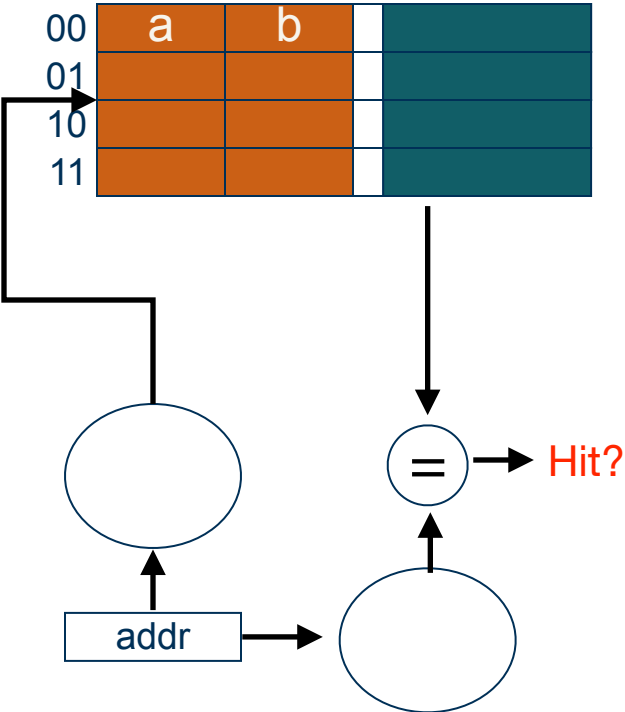
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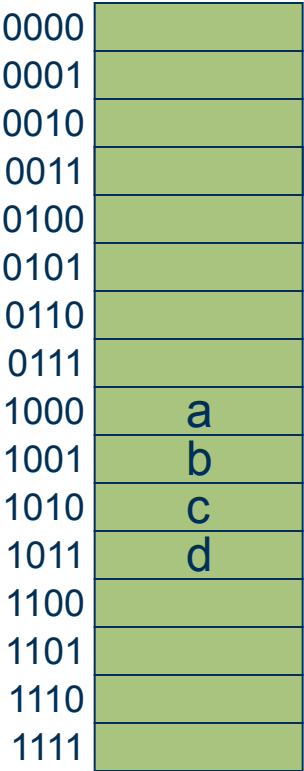
- Read 1000

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Cache



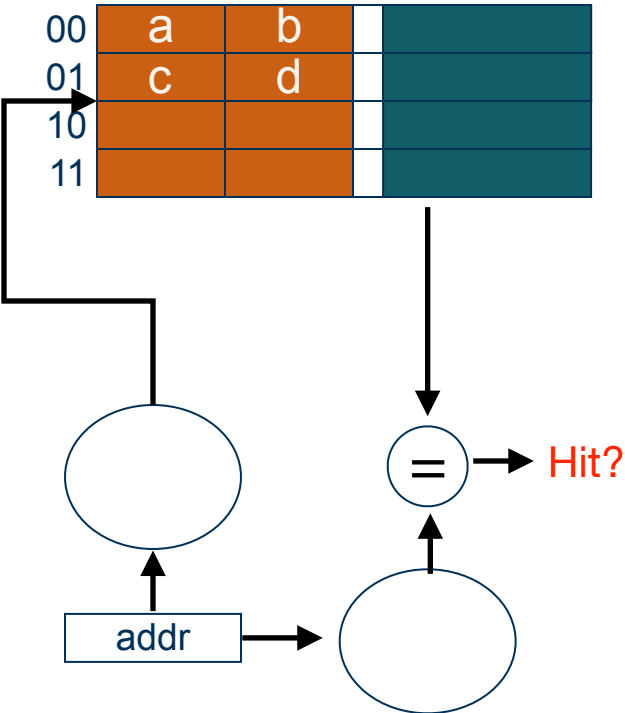
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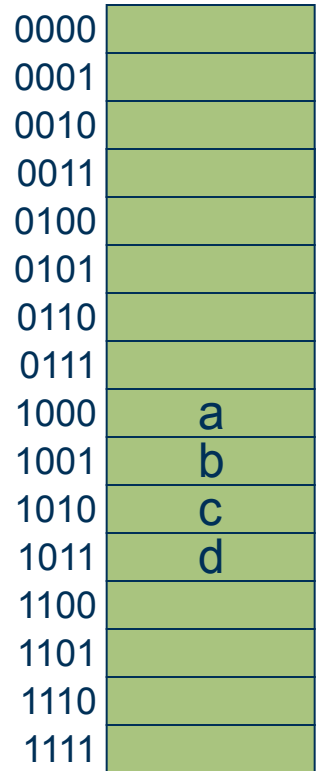
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- Read 1001 (Hit!)

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Cache



Memory

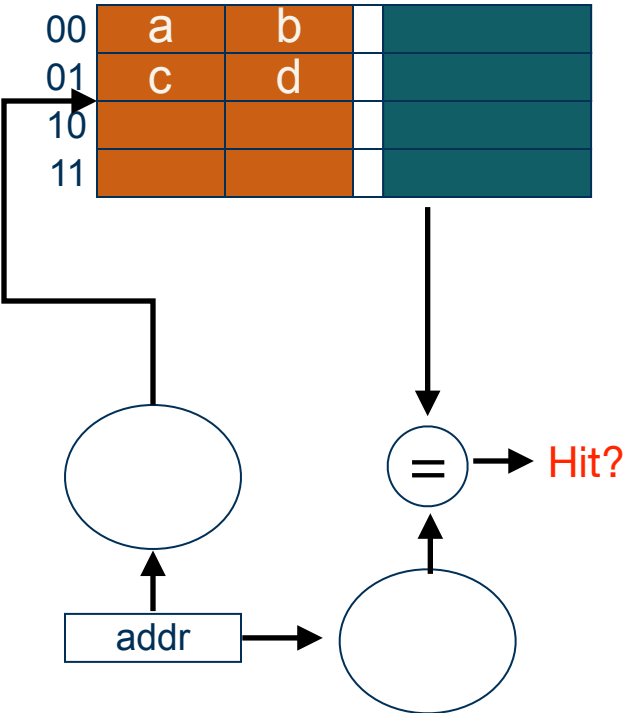


- Read 1000
- Read 1001 (Hit!)
- Read 1010

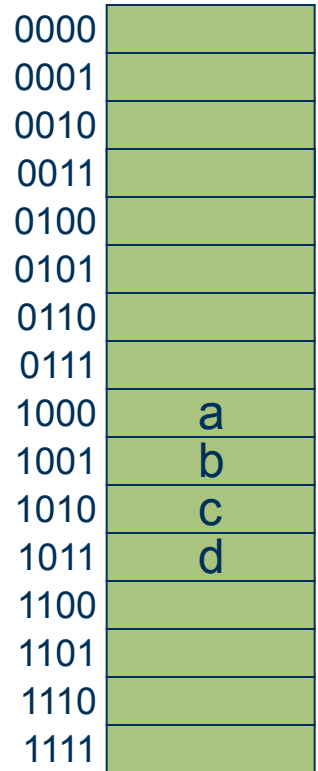


# Cache-Line Size of 2

Cache



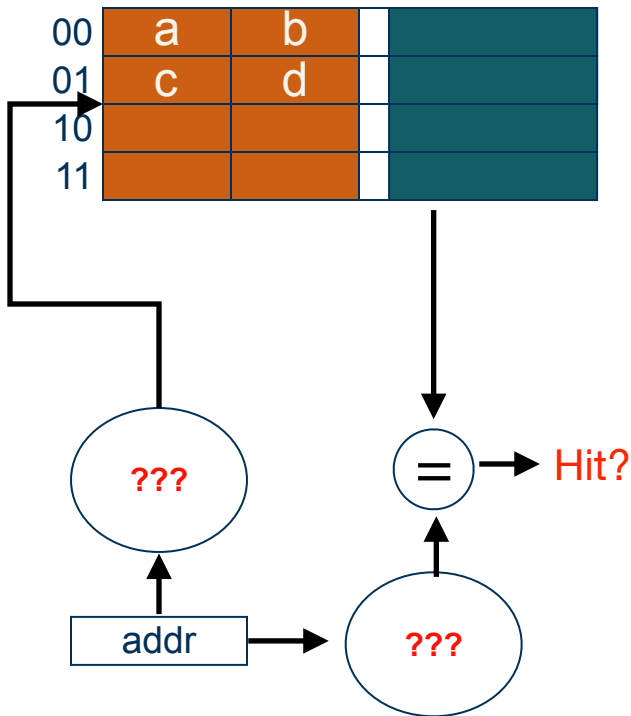
Memory



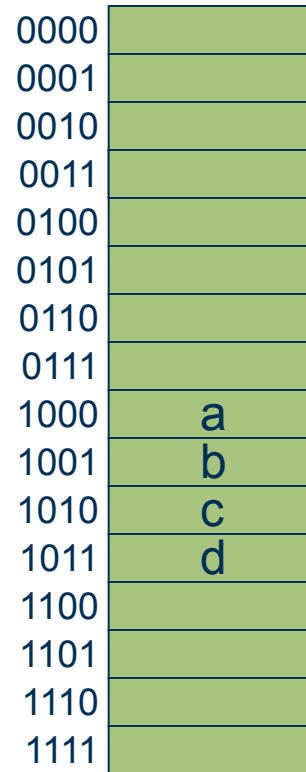
- Read 1000
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# Cache-Line Size of 2

Cache



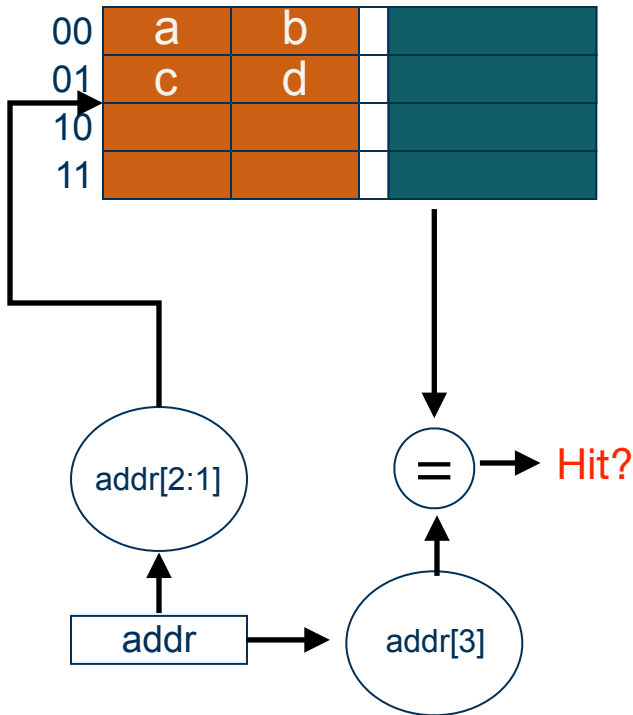
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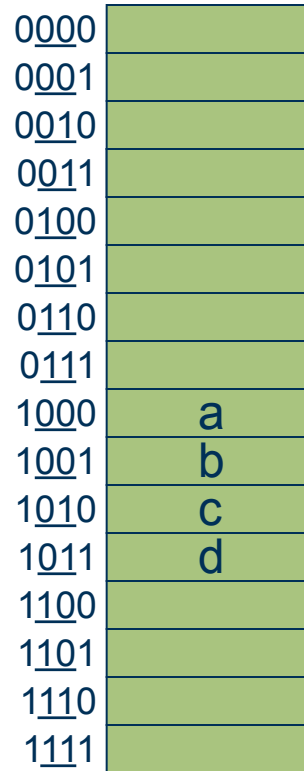
- Read 1000
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- Read 1010
- Read 1011 (Hit!)
- How to access the cache now?

# Cache-Line Size of 2

Cache



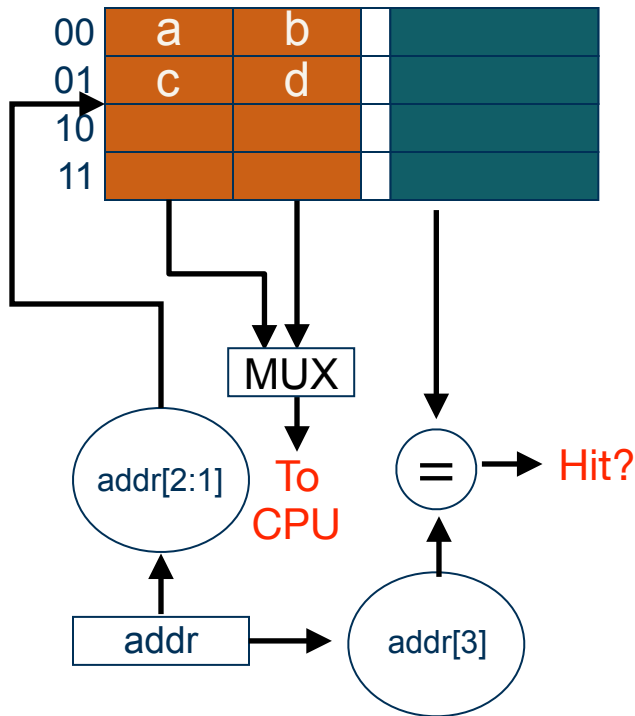
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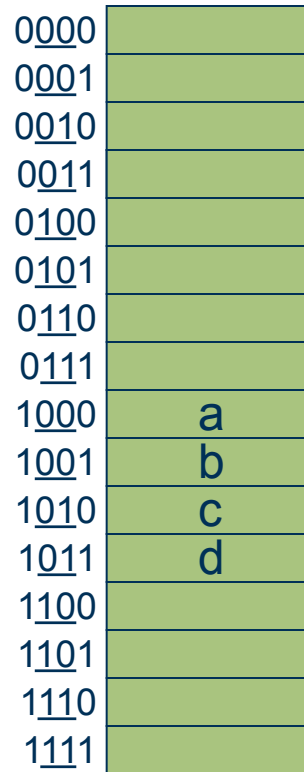
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## Cache



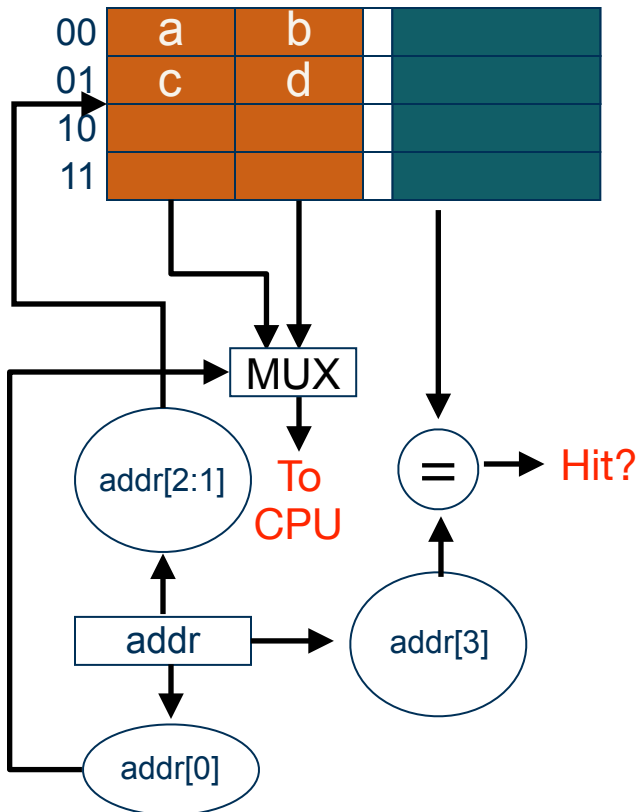
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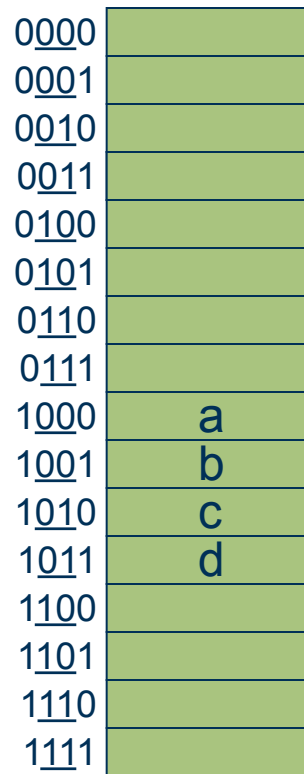
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## Cache



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# Cache Access Summary

- Assuming  $b$  bits in a memory address
- The  $b$  bits are split into three fields:
  - Lower  $l$  bits are used for byte offset within a cache line. Cache line size  $L = 2^l$
  - Next  $s$  bits used as index to find a set. Total sets  $S = 2^s$
  - The higher  $(b - l - s)$  bits are used for the tag
- Associativity  $n$  is independent of the the split between index and tag



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- Read miss: Put into cache
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- Read hit: Nothing special. Enjoy the hit!

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- Implication: value in cache will be different from that in memory!
- When do we write the modified data in a cache to the next level?
  - Write through: At the time the write happens

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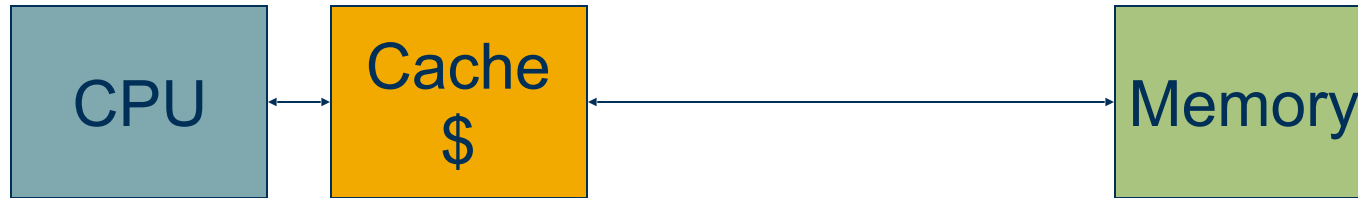
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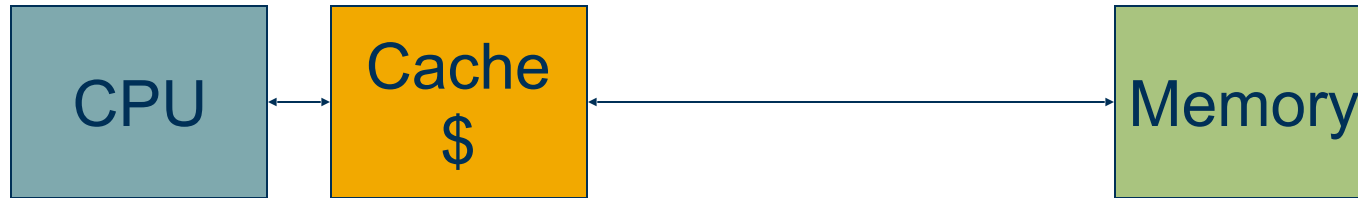
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Where do we place the unified cache for fast access?
- First level caches are almost always split
  - Mainly for the last reason above
- Second and higher levels are almost always unified

# General Rule: Bigger == Slower



- How big should the cache be?
  - Too small and too much memory traffic
  - Too large and cache slows down execution (high latency)

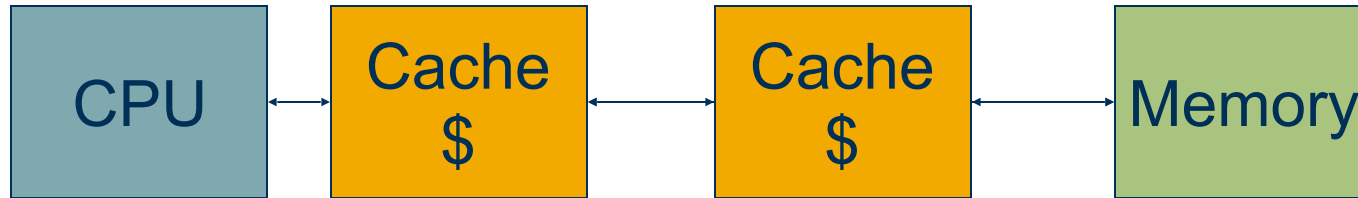
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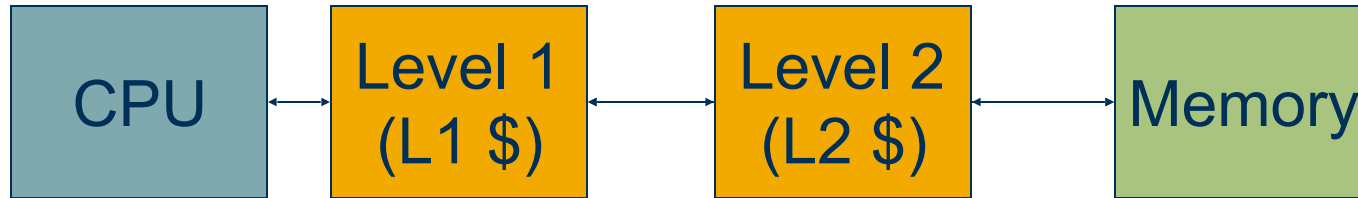


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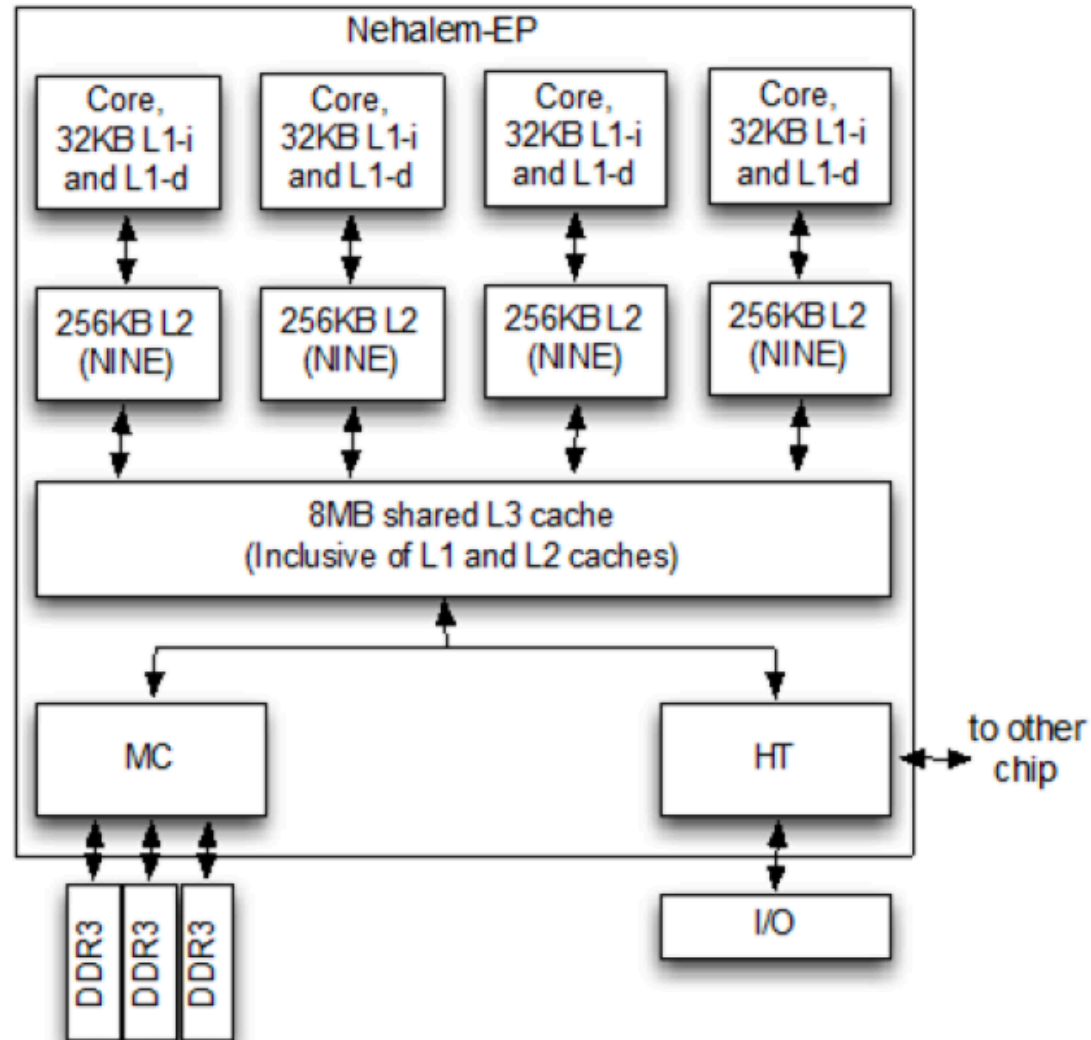
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# A Real Intel Processor



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    - Approximation: Least recently used (LRU)

# Implementing LRU

- Idea: Evict the least recently accessed block
- Challenge: Need to keep track of access ordering of blocks
- Question: 2-way set associative cache:
  - What do you need to implement LRU perfectly? One bit?

Cache Lines

0

1

LRU index (1-bit)



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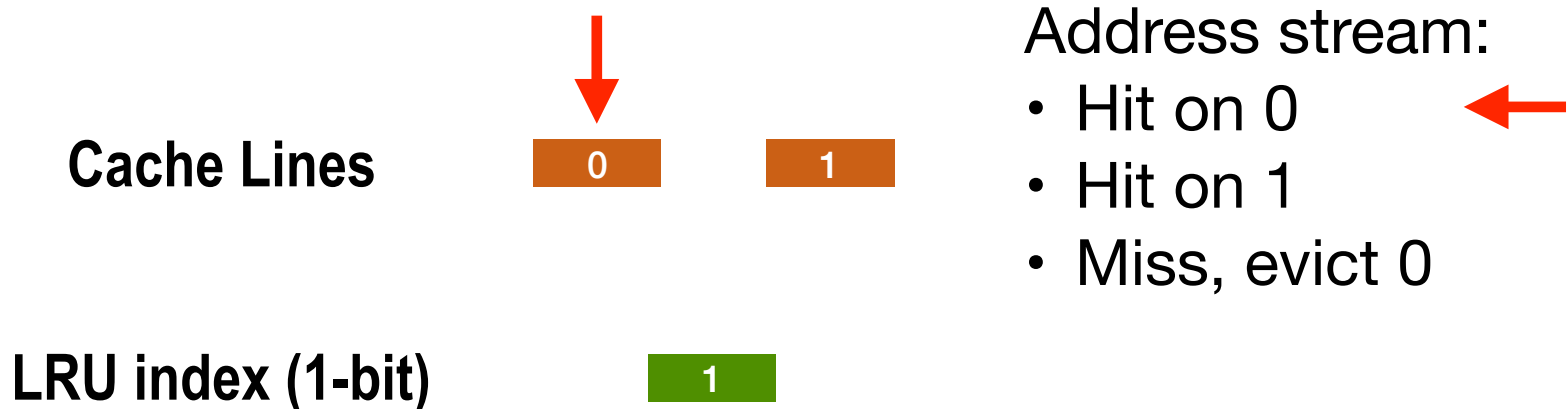


Address stream:

- Hit on 0
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- Miss, evict 0

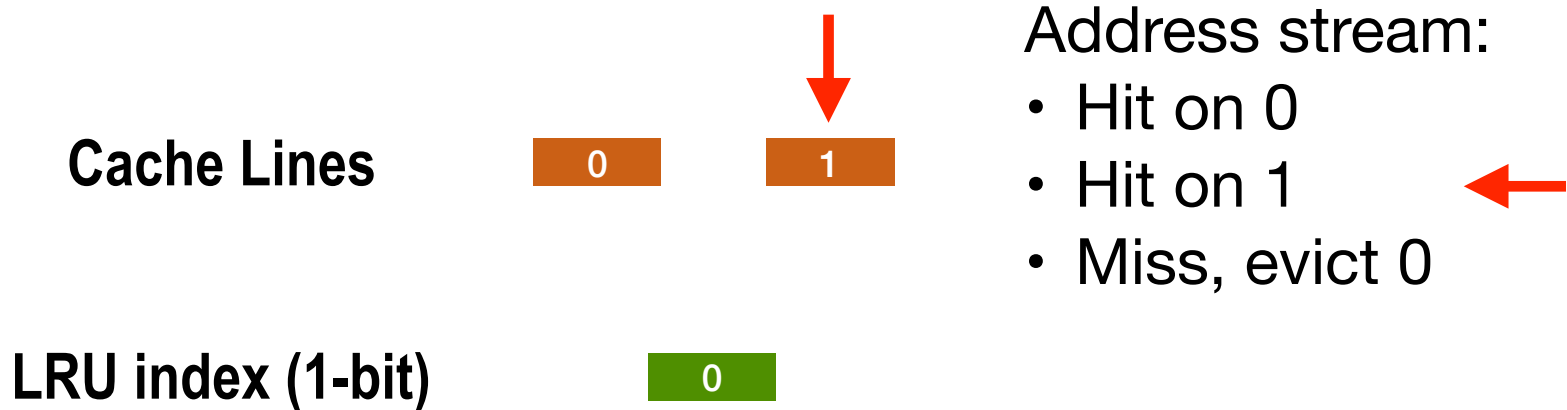
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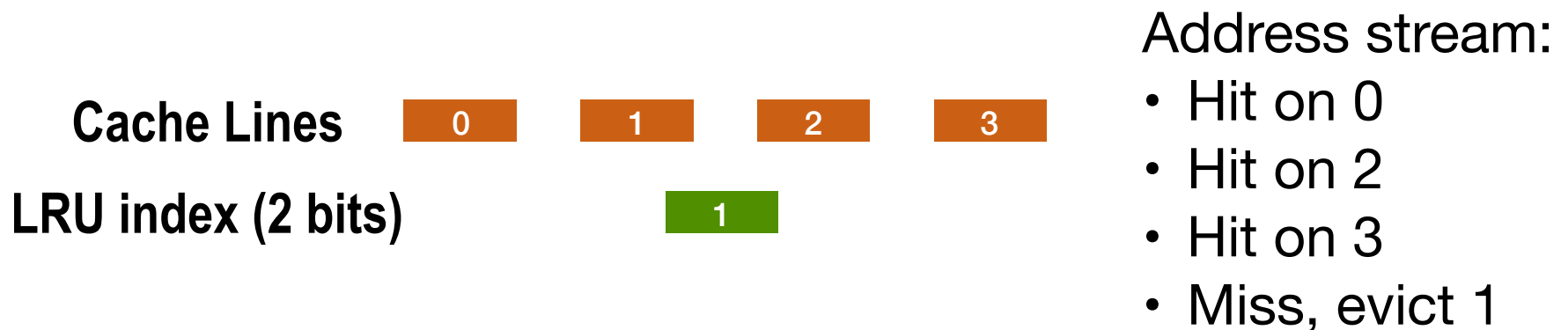


Address stream:

- Hit on 0
- Hit on 2
- Hit on 3
- Miss, evict 1

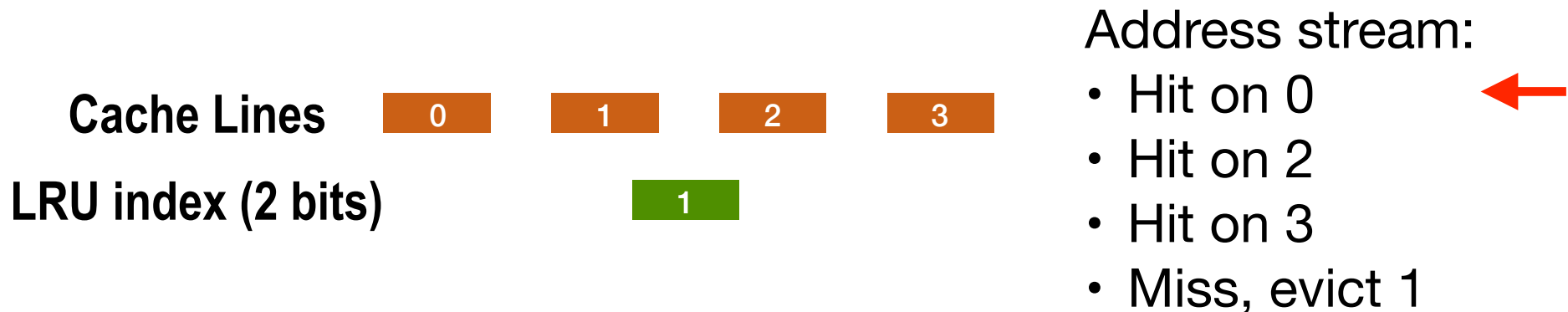
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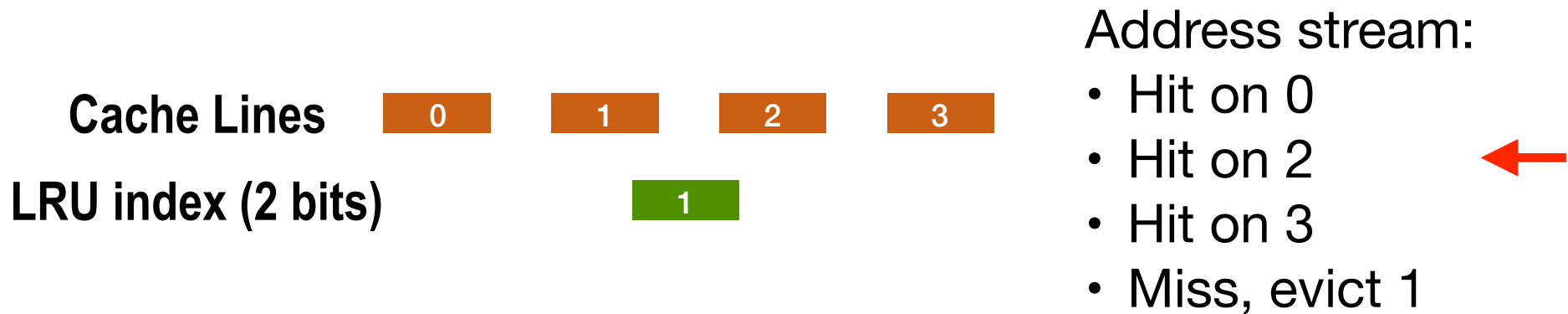
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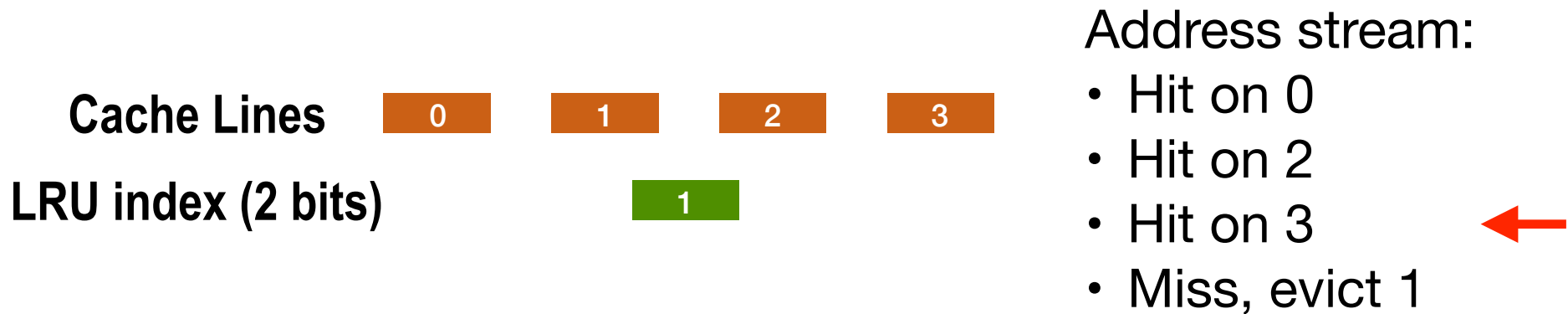
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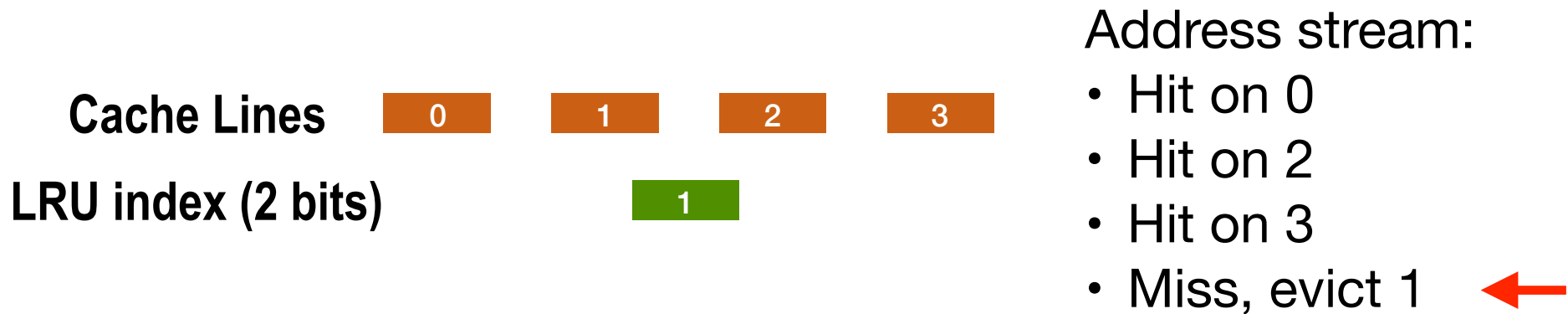
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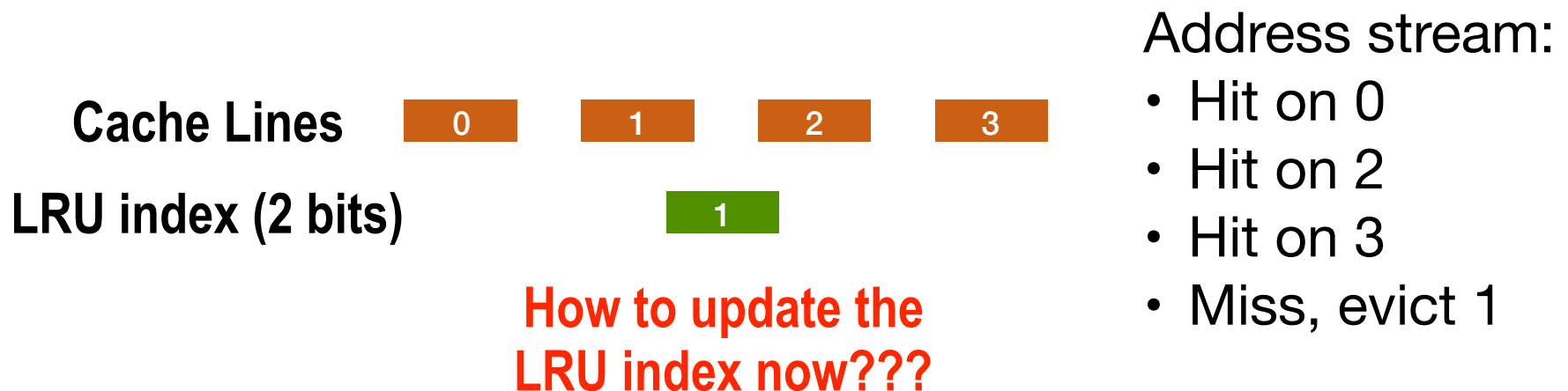
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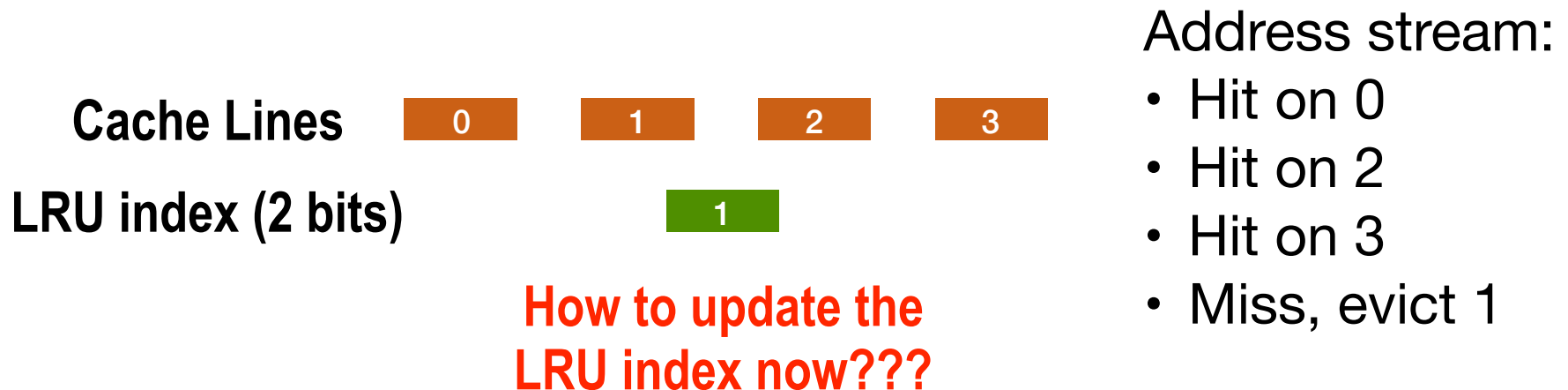
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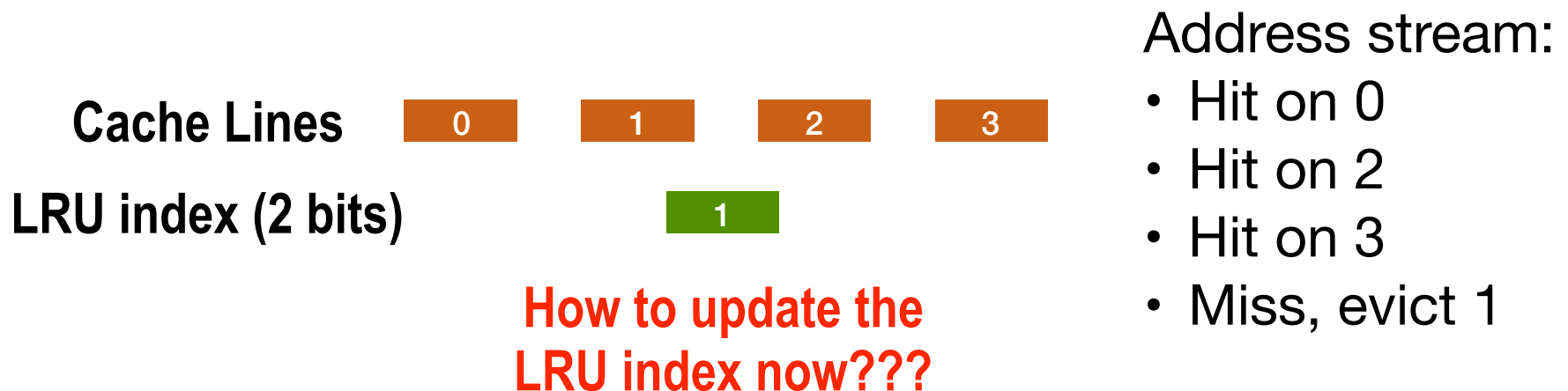
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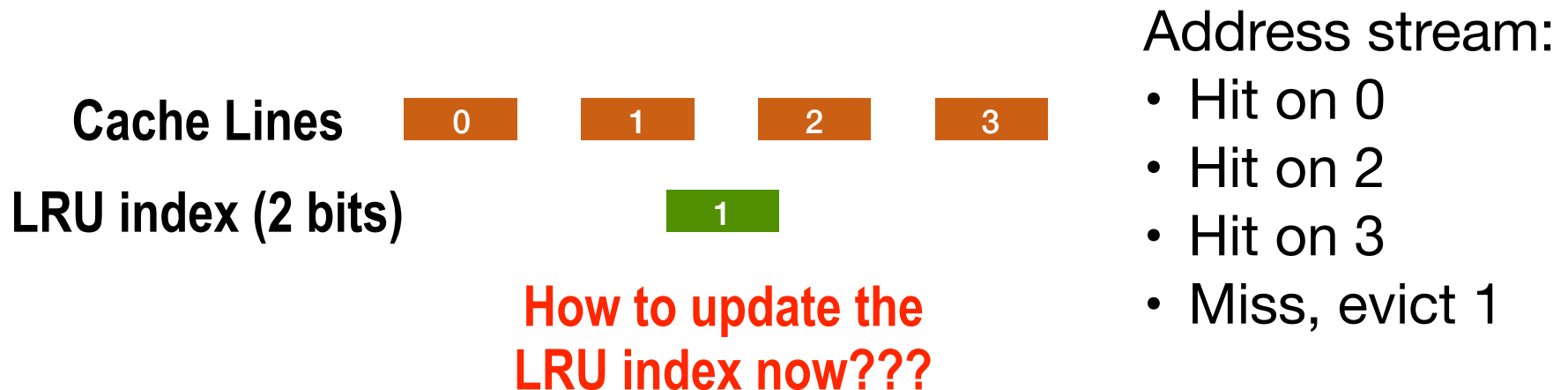
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  - In reality, true LRU is never implemented. Too complex.
  - “Pseudo-LRU” is usually used in real processors.

Cache Lines    0    1    2    3

LRU index (2 bits)

1

**How to update the LRU index now???**

Address stream:

- Hit on 0
- Hit on 2
- Hit on 3
- Miss, evict 1