CSC2/455 Software Analysis and Improvement Loop Transformations

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URCS

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Running Example

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Dependences?



The statements in this loop do not have any dependence.



Execution Order (Default)

$\begin{bmatrix} [0, 0] & [1, 0] & [2, 0] & [3, 0] & [4, 0] & [5, 0] & [6, 0] & [7, 0] \\ & [1, 1] & [2, 1] & [3, 1] & [4, 1] & [5, 1] & [6, 1] & [7, 1] \\ & & [2, 2] & [3, 2] & [4, 2] & [5, 2] & [6, 2] & [7, 2] \\ & & & [3, 3] & [4, 3] & [5, 3] & [6, 3] & [7, 3] \\ & & & [4, 4] & [5, 4] & [6, 4] & [7, 4] \\ & & & & [5, 5] & [6, 5] & [7, 5] \\ \end{tabular}$

Assuming row-major ordering, what can you say about the locality of this execution order?

Execution Order (New)

[0, 0] [1, 0] [1, 1] [2, 0] [2, 1] [2, 2] [3, 0] [3, 1] [3, 2] [3, 3] [4, 0] [4, 1] [4, 2] [4, 3] [4, 4] [5, 0] [5, 1] [5, 2] [5, 3] [5, 4] [5, 5] [6, 0] [6, 1] [6, 2] [6, 3] [6, 4] [6, 5] [7, 0] [7, 1] [7, 2] [7, 3] [7, 4] [7, 5]

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Changing the order

```
for(i = 0; i <= 5; i++) {
   for(j = i; j <= 7; j++) {
      Z[j, i] = 0;
   }
}</pre>
```

What would the loop indices need to be if I wanted to execute j as the outermost loop?

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```
for(j = ?; j <= ?; j++) {
   for(i = ?; i <= ?; i++) {
      Z[j, i] = 0;
   }
}</pre>
```

New Loop Bounds

```
for(j = 0; j <= 7; j++) {
   for(i = 0; i <= min(5, j); i++) {
      Z[j, i] = 0;
   }
}</pre>
```

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The Problem

Given:

a set of affine constraints (inequalities) defining the iteration space

- ▶ an "preferred" execution order
- Can we generate a set of loop bounds for each loop in the loop nest?

Running Example

$$0 \le i$$
$$i \le 5$$
$$i \le j$$
$$j \le 7$$

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Order i (innermost loop) to j (outermost loop)

What are the loop bounds for j?

Let's eliminate *i*:

$$0 \le i$$
$$i \le 5$$
$$i \le j$$
$$j \le 7$$

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Loop bound for j(1)

Rearrange equations so that they are all in the form:

$$L \leq c_1 x_m \\ c_2 x_m \leq U$$

- \triangleright c_1, c_2, \dots are constants, x_m is the index variable
- L and U are constraint expressions (possibly containing other variables)

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• yields new constraint: $c_2 L \le c_1 U$ with x_m eliminated!

What are the loop bounds for *j*? Let's eliminate *i*:

$$\begin{array}{rrr} 0 & \leq & 1i \\ & 1i \leq 5 \\ & 1i \leq j \\ & j \leq 7 \end{array}$$

yields:

$$\begin{array}{rrrr} 0 & \leq & 5 \\ 0 & \leq & j \\ & & j \leq 7 \end{array}$$

What are the loop bounds for *i*? Let's eliminate *j*:

$$\begin{array}{rrrr} 0 & \leq & i \\ i & \leq & 5 \\ i & \leq & 1j \\ & & 1j \leq 7 \end{array}$$

yields:

$$\begin{array}{rrrr} 0 & \leq & i \\ i & \leq & 5 \end{array}$$

i

Results

- ▶ 0 <= j <= 7 when i eliminated
- 0 <= i <= 5 when j eliminated but this is original loop bounds

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- not entirely unsurprising!
- This method is called Fourier–Motzkin elimination
 - Can project one dimension at a time
 - Now, need to iteratively construct projections

Fourier-Motzkin Elimination

- S is the original set of iteration space constraints
- C is the set of constraints involving x_m
- Form constraint c₂L ≤ c₁U with x_m eliminated for each pair of L and U in C
 - Add to set C_{new} if satisfiable
 - Else projection is not possible since S is unsatisfiable (and hence contains 0 points)

• The projection is $S' = S - C + C_{new}$

Algorithm 11.11 in the Dragon Book.

Computing New Loop Bounds Iteratively

• Let S_n be the original iteration space constraints

• Let ordering of variables be v_1 (outermost) to v_n (innermost)

• I.e.
$$v = [j, i]$$

In reverse order i from n to 1:

- Let L_{v_i} be lower bound constraints on v_i in S_i
- Let U_{v_i} be upper bound constraints on v_i in S_i
- Let S_{i-1} be the result of Fourier-Motzkin elimination of v_i in S_i

In order of v₁ to v_n:

Remove any redundant constraints in L_{vi} and U_{vi} implied by cumulative previous lower bound and upper bound constraints

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Figure 11.15 in the Dragon Book.

For our example



More than permutations: Traversal Axis

- Original loop was iteration in 2-D space.
 - Say, j was x-axis and i was y-axis
- Original loop with *i* outermost traversed "horizontally" (along x-axis) first

- Outermost j traversed "vertically" first
- Now we want to traverse "diagonally"

How can we traverse diagonally?

[0, 0] [1, 1] [2, 2] [3, 3] [4, 4] [5, 5] [1, 0] [2, 1] [3, 2] [4, 3] [5, 4] [6, 5] [2, 0] [3, 1] [4, 2] [5, 3] [6, 4] [7, 5] [3, 0] [4, 1] [5, 2] [6, 3] [7, 4] [4, 0] [5, 1] [6, 2] [7, 3] [5, 0] [6, 1] [7, 2] [6, 0] [7, 1] [7, 0]

Add new constraints

▶ k = j − i is a constant in inner loop, increasing from 0 to 7 across outer loop

Substitute i = j - k in the original constraints:

0 ≤ j − k ≤ 5
 i − k < i < 7

Order loop in k, j order

Result

```
for(k = 0; k <= 7; k++) {
   for(j = k; j <= min(7, 5 + k); j++) {
      Z[j, j - k] = 0;
   }
}</pre>
```

If loop traversal order can be specified as an affine transformation, then the loop bounds can be generated as usual.

- Not all traversal orders are affine
- Deciding which axis to traverse is a harder problem
 - For example, to improve locality or parallelism or both!

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Recall transformations from last class.

Affine Transformations Workflow

- Identify loops with affine iteration spaces
- Compute dependences
- Figure out transforms of affine spaces
 - must respect dependences
 - may optimize other metrics (e.g. locality, parallelism)

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- Generate loops such that:
 - Dependence constraints are met
 - Transformed iteration space constraints are met
- Parallelize resulting loops
 - Vectorization
 - Software Pipelining

Software Pipelining

```
for(i = 1; i <= m; i++)
for(j = 1; j <= n; j++)
X[i] = X[i] + Y[i, j];</pre>
```

Inner loop is sequential

Outer loop can be parallelized

Processor i handles loop iteration i of outer loop

Each iteration of the inner loop is executed on a different processor, with data being passed from one processor to another.

P0 P1 P3 X[1] += Y[1,1] X[2] += Y[2,1] X[1] += Y[1,2] X[3] += Y[3,1] X[2] += Y[2,2] X[1] += Y[1,3] X[4] += Y[4,1] X[3] += Y[3,2] X[2] += Y[2,3] X[4] += Y[4,2] X[3] += Y[3,3]X[4] += Y[4,2] X[3] += Y[3,3]

What are the advantages of doing this?

Stuff we did not cover

- Loop tiling/blocking
 - Simple, see textbook
- Many other loop transformations
 - See the slides in the readings on polyhedral compilation posted on Blackboard

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References

Chapter 11 of the Dragon Book

Section 11.3.2 of the Dragon Book

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Section 11.9 of the Dragon Book